Heat Exchanger Performance and Optimisation

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by

Terrence Clarke

Supervised by

Dr Khalid Saleh

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Abstract

Heat exchangers are used throughout industry, in various forms, to remove excessive heat created and allow continual operation of the equipment. A common type of heat exchanger is the liquid/liquid non-direct heat exchanger, typically with flow rates adjusted using a butterfly control valve to maintain desired operating temperatures. A modern option for reducing some of the system inefficiencies of heat exchangers is replacing the fixed output pump and butterfly control valve system with a variable speed pump which does not require a control valve. This improvement provides:

- Improved efficiency as the variable speed pump uses less power
- Longer pump life by reducing cavitation from throttling
- Longer life and efficiency out of the heat exchanger core due to less 'hot-spots' resulting in fouling.

An extensive literature review was carried out, however little published information is available on the effects of a butterfly control valve at the entry of a heat exchanger. This dissertation investigates the knowledge gap surrounding the influence of a control valve at the entry of a heat exchanger. It addresses both the global heat distribution and the local transfer wall temperatures near the entry region. The following stepwise phases were completed in succession and form the structure of this investigation:

- Phase 1: Conduct physical experiments of a simple heat exchanger arrangement and gather experimental data
- **Phase 2**: Undertake a computational fluid dynamics (CFD) simulation of a heat exchanger modelled on the physical experiment
- **Phase 3**: Compare the results of the experimental and simulation studies. Refine the CFD model until the results are within an acceptable error range
- **Phase 4:** Conduct a physical experiment and CFD modelling of a simple heat exchanger using a control valve at the process water entry point and analyse the temperature distribution at a global level.
- **Phase 5:** Analyse the temperature distribution at the entry of the heat exchanger for localized hot spots on the transfer wall
- **Phase 6:** Scale the CFD model to the size and boundary conditions of the real-life application and repeat global and localized analysis.

With respect to the global heat distribution, the study found that both the USQ experimental jig and scaled analysis showed no influence from the control valve at the entry. However, for the local transfer wall distribution, the simple experimental jig and the scaled analysis both showed that the maximum temperature on the wall was significantly higher in the region 1.9 to 2.9x the diameter of the valve diameter into the heat exchanger. The study also found that as the angle of the control valve became more closed, both the average and maximum temperature across the transfer wall in the 1.9-2.9x valve diameter region increased.

These results indicate a variable speed pump reduces temperature spikes on the transfer wall and is preferable to a fixed speed pump with butterfly control valve.

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Certification

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Terrence Braden Clarke



12 October 2021

Signature

Date

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Nomenclature

A	Area (m^2)
c _p	specific heat $(\frac{J}{kg \kappa})$
CFD	Computational Fluid Dynamics
CLCS	Closed Loop Cooling System
D	Diameter (m)
e	Energy per unit mass (J)
h	Heat Transfer Coefficient $(\frac{W}{m^2 K})$
ННР	High Horsepower
HVAC	Heating, Ventilation and Air Conditioning
K_{eff} or λ	Thermal Conductivity $\left(\frac{W}{m K}\right)$
Lpm	Litres per minute
'n	Mass flow rate $(\frac{kg}{s})$
ρ	Density $(\frac{kg}{m^3})$
р	Fluid pressure (Pa)
Ż	Heat Energy Transfer (W)
Re	Reynolds Number
Т	Temperature (K)
ΔT_m	Mean Temperature Difference (K)
U	Overall heat transfer coefficient $\left(\frac{W}{m^2 K}\right)$
USQ	University of Southern Queensland
μ	Viscosity $(\frac{kg}{ms})$
V or Q	Flow rate $(\frac{m^3}{s})$

Glossary of Terms

Adiabatic:	A process in which no heat is transferred in or out of a system.
Annulus:	The area between two concentric circles.
Baffle:	A device to restrain the flow of fluid.
Boolean:	A process in ANSYS software to add or subtract two bodies.
Chamfer:	A cut out on an edge of corner.
Computational Fluid Dynamics:	Use of computer programs to perform analysis and solve problems involving fluid flows.
Computations:	Mathematical calculations.
Concentric:	Having a common centre.
Dynamometer:	A device for measuring the speed and torque of an engine.
Eddies:	Swirling of fluid in turbulent fluid flow.
Electric field:	A physical field around electrically charged particles which can influence other particles.
Extrude:	A process in ANSYS for extending a 2D sketch in a linear direction to form a 3D shape.
Geometries:	Dimensional properties of an object including size, shape, and position.
Iterations:	Repeating of a process using the previous results as the start of the process.
Logarithmic:	The inverse function of an exponential which can be used to display numerical values of a wide range in a compact way.
Maldistribution:	Uneven distribution of something.
Methodologies:	A system of methods used to solve a problem.
Nucleate boiling:	A stage of the boiling process which produces bubbles.
Negligible:	So small or unimportant it can be ignored.
Oscillation:	Repetitive variation around a central value.
Out-of-chassis engine:	An engine which has been removed from, or not yet fitted to, its normal operating location.
PID controller:	A control system which uses current, past, and expected future performance to control the system.

Solubility:	Degree of which a substance will dissolve into a solvent.
Tetrahedron:	A triangular pyramid 3-dimensional shape.
Thermocouples:	An electrical device made of two dissimilar metals used to measure temperature.
Volume:	The amount of space and object occupies.

1.0 Chapter 1: Introduction

1.1 Background

There are many industrial applications generating heat that could not be used for their intended purpose without appropriate cooling. There are also many everyday devices that generate little heat, such as a modern lightbulb not requiring specialised cooling. In contrast some heavier equipment and plant generate significant amounts of heat, so much so, they fail or become ineffective without a cooling solution. They include cooling engines in vehicles used to transport people and goods, electrical motors used to drive conveyors and computers using specialized heat sink plates. Some of the common cooling components used throughout current industry are:

- Air/liquid radiators for moving stock
- Air/solid heat sinks, often in combination with a fan
- Cooling Towers
- Heating, ventilation, and air conditioning (HVAC) environments
- Liquid/liquid or liquid/gas heat exchangers.

This study focuses on indirect type liquid/liquid heat exchangers. These are commonly used to cool industrial systems by cooling the equipment's oil or coolant using process water as a cooling liquid. A heat exchanger is used to transfer heat from a hot liquid or gas to a cool liquid or gas without mixing the fluids. To achieve this, the two fluids are run through a series of fluid paths separated by a highly conductive thin wall. The heat energy transfers very effectively through the thin wall conductive material exchanging from the hot fluid to the cold fluid.

An example of an industrial scenario, and the focus of this study, is the cooling of a stationary engine during dynamometer performance testing. An out-of-chassis engine connected to a dynamometer does not have the vehicle's radiator and fan system so the engine needs to be cooled by different means. To best represent the vehicle's radiation and fan system, and provide corrosion protection to the engine, a closed loop cooling system (CLCS) is often used. A CLCS runs a circuit of coolant/water mixture through the engine which transfers the heat generated to process water through a heat exchanger. The process water is subsequently cooled by cooling towers. If the process water side is simplified and considered a constant low temperature source, the cooling system can be represented with a simple system diagram as shown in Figure 1-1 below.



Figure 1-1: Engine dynamometer cooling system (Icons made by Freepik from <u>www.flaticon.com</u>).

For the engine to operate within its normal operating temperature range, the cooling process water flow rate needs to be controlled to prevent over cooling. Traditionally this has been achieved by using a simple temperature control system closing and opening a valve on the heat exchanger process water inlet connection.

1.2 Idea Generation

The author of this study works for a business which carries out dynamometer testing of large engines to validate their performance against published performance ratings as a critical part of the overall testing regime. Recently the business has been looking at replacing an aging, inefficient system with a modern system. A specialist equipment supplier has provided sales material claiming their product is superior to their competitors. They advise their product uses a control system which utilises a variable speed pump instead of the traditional approach of using a fixed output pump with the flow throttled using a control valve. The anecdotal advantages advised by the sales team were as follows:

- Improved efficiency as the variable speed pump uses less power
- Longer pump life by reducing cavitation from throttling
- Longer life and efficiency out of the heat exchanger core due to less 'hot-spots' resulting in fouling.

The first two advantages are intuitively correct. However, the third effect is not something that has been revealed by the authors career experience or undergraduate studies. This intriguing claim is the subject of the authors final year dissertation.

1.3 Expected Outcomes

It is hypothesized that the use of a control valve at the heat exchanger process water entry could create turbulence and other entry conditions impacting on both the global temperature distribution and localised heat distribution in the entry region transfer wall.

The aim of this dissertation is to simulate the entry effects of a control valve in the entry region of heat exchanger using computation fluid dynamics (CFD) software to validate if the entry affects will produce a temperature distribution different to a variable speed pump. This will be tested at both a global and local sense within the heat exchanger in experiments that can be verified with physical experiments and scaled experiments to replicate real industrial conditions.

2.0 Chapter 2: Literature Review and Knowledge Gap

An extensive literature review was undertaken to understand existing knowledge surrounding heat exchanger modelling and verify that a knowledge gap exists. This dissertation will provide a valuable content to field some of that gap. The concepts reviewed are:

- Heat exchanger technologies
- Heat exchange efficiency improvements
- Inefficiencies within head exchangers, especially around fouling and flow distribution
- Existing studies on the entry region of heat exchangers
- Previous CFD modelling of heat exchangers
- Control valve types
- Butterfly valve modelling
- Any existing similar studies available.

2.1 Heat Exchanger Technologies

Three common type of heat exchangers are used in industry today:

- Direct-contact heat exchangers
- Storage-type heat exchangers
- Indirect-contact heat exchangers.

2.1.1 Direct Contact Heat Exchangers

Direct-contact heat exchangers transfer heat by direct mixing of two fluids. Direct-contact heat exchangers produce much higher transfer rates, are less expensive and reduce fouling rates (Shah & Sekulic 2003). Examples of these methods in industry are direct water mixing chambers and water/air cooling towers.

Where flow rates of fluids cannot be changed (fixed pumps or controlled by up/down stream process) a common method of controlling the desired temperature is by means of 'bypassing' (Luyben 2011). Bypassing involves taking a portion of the fluid stream and routing around the heat exchanger. The control speed can be accelerated by mixing both control and process bypass streams rather than routing through the heat exchanger (Luyben 2011). This method is known as steam-blending and is only practical if both the control and process fluid are the same fluid.

The methods of direct mixing or bypass mixing would not be applicable in the application of this study as two different fluids are used and mixing is undesirable.

2.1.2 Storage-Type Exchanger

In a storage-type heat exchanger, the fluids flow through the same passage at alternate times. Heat is transferred from the hot fluid and stored in the heat exchanger material walls. The cold fluid then flows through the exchanger and the heat transfer from the material walls to the cold fluid (Shah & Sekulic 2003). In this type of exchanger, there will always be some fluid transfer due to flowing through the same passages.

2.1.3 Indirect-Contact Heat Exchangers

Indirect-contact heat exchangers are devices designed to allowed heat transfer between two fluids without allowing the fluids to mix (Cengel, Ghajar 2015). Two fluids flow through the heat exchanger in two different passages and heat is continually transferred from the hot to cold fluid through a thin conductive metal wall (Shah & Sekulic 2003). These heat exchangers come in several arrangements depending on applications. The common construction types are:

- Tubular shell and tube
- Extended surface
- Regenerative
- Plate.

Tubular: Tubes, usually circular, of high conductive metal are bent in various shapes and configurations to meet the performance, fluid properties and sizing constraints. Tubular exchangers are very common in industry for liquid-to-liquid applications. Tubular construction exchangers can be further broken down in to:

Shell and Tube: A bundle of round tubes in a cylindrical shell parallel to the tubes. One fluid flows through the tubes and one through the shell. This is the most common liquid/liquid type exchanger found in industry (Cengel, Ghajar 2015). Baffles are often used to ensure the shell fluid flows where desired and support the tubes.



Figure 2-1: A typical single pass tube and shell heat exchanger arrangement (Shah & Sekulic 2003).

Double-Pipe: This is the simplest design of heat exchanger with two concentric round tubes separated by thin wall of conductive metal material. One fluid flows through the inner tube and one fluid through the outer tube.



Figure 2-2: A typical double pipe heat exchanger arrangement (Shah & Sekulic 2003).

Plate-type: These heat exchanger systems are built of a series of plates with hot and cold circuits through them. The thin plates can then be joined together (with gaskets, weld or braising) in an enclosure/frame. The two fluids then flow through main galleries and in/out of each plate. There are many different plate designs in the industry with different performance characteristics for different fluids and applications. These plate-type exchangers are considered much more efficient as the transfer wall has much more surface area for the fluid to be exposed to (Aghayari et al 2015).



Figure 2-3: A typical gasketed plate-type heat exchanger arrangement (Shah & Sekulic 2003).

In all construction types, there are three common flow configurations (Ahmed, Mesalhy & Abdelatief 2015):

- Parallel flow both fluids flow in the same directions through the heat exchanger
- Counter flow the two fluids flow in opposite directions through the heat exchanger
- Cross-flow fluids cross perpendicularly through the exchanger.

In a parallel flow arrangement, the hot and cold entry points are at the same end of the heat exchanger. The counter-flow arrangement is the opposite with the entry points of the fluids on opposite ends of the exchanger

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core. The parallel arrangement is rarely used in industry as the counter-flow arrangement reduces thermal stresses, can transfer more heat, and produce a more uniform transfer rate through the exchanger (Engineers Edge 2021). Cross flow exchangers are used mostly in fluid to air coolers where gases (usually air) flow over the fluid domain. A common example of this is a car radiator.

2.2 Heat Exchanger Efficiency and Optimisation

With any technology, manufactures are always trying to make efficiency improvements to increased performance whilst minimizing the volumetric footprint and weight of the hardware. There are two methods of doing this (Sharifi et al 2018):

- Passive methods: improving the material or geometry of the exchangers to improve performance; for example, adding fins or coiled wire inserts.
- Active methods: adding energy to improve performance; for example, adding vibrational flow.

Some examples of these improvement are also mentioned in a study by Ahmed, Mesalhy & Abdelatief (2015), and include:

- Passive methods of improving fin surface area designs and adding vortex generating geometry to the fins such as slits, louvers, and serrations
- Active methods of adding electric or acoustic fields, moving mechanical devices and/or adding vibration to the surfaces.

The literature review found studies on improving heat exchanger design through these methods, however they add little value to the interest of this study so are not being pursued further.

2.3 Heat Exchanger Inefficiencies

2.3.1 Heat Exchanger Flow Maldistribution

Flow maldistribution occurs where the fluids are not uniformly distributed at the heat exchanger inlets and/or throughout the heat exchanger core (Shah & Sekulic 2003). The term maldistribution is not to be misunderstood with one of the key concepts being investigated in this study – temperature maldistribution. Flow maldistribution of fluids most commonly occurs in multi-channel heat exchangers like plate or fin crossflow exchangers. Flow maldistribution can be induced by:

- Geometry
- Operating conditions
- Poor design.

A recent study by Denkenberger et al. (2021), compared mathematical models of heat exchangers to CFD models to investigate the flow maldistubtion effects on the performance of the exchangers. This study produced many datasets and plots that can help determine the effects of maldistrubtion at different flow rates and geometries including the different efficiveness of each channel. This study was however researching the

effects in multi-channel exchangers which is likely relevant to the application plate-style exchanges, but not so much the dual-wall type in this dissertaion.

Similarly, another recent study by Zang et al (2021), performs some mathematical modeling of cross flow heat exchangers to analyse the effects of maldistrubtion to the performance of the heat exchanger. This study concluded that for several key regions of the heat exchanger the maldistrubtion of the fluids can have significant influence of the performance of the system.

The findings of this literature are not directly valuable to the case in this disseration, but they do show that flow behaviour does affect the performance of the heat exchanger. This could possibly result in temperature maldistrubution throughout the heat exchanger core.

2.3.2 Heat Exchanger Fouling

Fouling of heat exchangers is the accumulation of undesirable material in the heat exchanger core resulting in poor performance of the heat exchanger (Shah & Sekulic 2003). This fouling is usually a deterioration of the heat transfer surface performance over time (Cengel & Ghajar 2015). The effects of fouling can be:

- Reduction in heat transfer
- Increased pressure drop
- Increase corrosion of the core

As a result of these affects, or in preventative attempts to mitigate these affects, fouling of heat exchangers can be expensive. Some examples of the costs of fouling include:

- Increases in component cost to ensure the heat exchanger serviceability
- Increases in maintenance costs cleaning, additives, etc.
- Loss of production from unexpected failures
- Energy loss from inefficiencies.

In mathematical modelling, the fouling effects are considered in calculations by adding the fouling factor (R_f) to the overall transfer coefficient (Cengel & Ghajar 2015). When designing an appropriate heat exchanger for an application that is likely to operate in conditions that could cause these fouling factors to occur, a larger heat exchanger would be required to account for the performance loss with time.

Fouling Mechanisms

There are three primary fouling mechanisms relevant to liquid\liquid heat exchangers (Shah & Sekulic 2003):

- Precipitation or crystallisation
- Corrosion
- Biological.

Precipitation or crystallisation: This phenomenon is the precipitation of dissolved salts on to the heat transfer surface when the surface concentration exceeds the solubility limit. This can occur both in the process and

controlled fluids and can occur both when fluids are being heated or cooled. This is the same kind of fouling noticed on everyday appliances like the inside of a kettle.

Corrosion: In some application chemical fouling can occur from corrosion of the transfer wall or outside wall surfaces. This corrosion can affect the transfer and flow performances.

Biological: Certain conditions can also cause algae growth and are considered a form of biological fouling.

It is noted in Cengel & Ghajar (2015), that fouling increases with increases in temperature and decreasing velocity.

2.3.3 Heat Exchanger Nucleate Boiling

Nucleate boiling is a very complex chaotic phenomenon that occurs when there is a temperature difference between the transfer wall and fluid of between 5 and 30 degrees (Cengel & Ghajar 2015). Nucleate boiling is where bubbles and possible vapour voids occur near the surface and in the fluid. These bubbles can affect the heat transfer rate of the heat exchanger.

An example investigating how nucleate boiling can affect heat exchanger transfer rate can be seen in a study by Chun & Kang (1996). In this study, vertical and horizontal tube arrangements of varying diameters were tested to investigate the nucleate affect. One of the key outcomes of their study was an improved heat transfer rate from the bubbles and turbulence caused by the nucleate boiling. Contrary to this it was found the large vapour voids caused by nucleate boiling cause a reduction in heat transfer.

Due to the complex nature of this phenonomen, and the difficultly in modeling it, it is being omited from the study. It is worth noting that this phenonmen could possibly be an area of extra study to see if the temperature in the localised temperature spikes could cause excessive nucleate boiling.

2.4 Heat Exchanger CFD modelling

2.4.1 Mathematical Modelling

There are three common methods of mathematically modelling heat exchangers (Lazarevic et al 2019):

- Basic energy balance formulation
- Log mean temperature difference (LMTD)
- Effectiveness number of transfer units (εNTU).

The log mean temperature method is the primarily used in European regions and the ($\varepsilon - NTU$ method is mainly used in the USA. Both methods are valid and can both be useful depending on the known values of the application. The LMTD is valuable if the inlet and outlet temperatures are known and can be difficult to use in finding missing temperature values, though not impossible. The NTU method is good if the cooling specifications of the heat exchanger are given and the inlet or outlet temperatures need to be calculated.

From these methods, and using other fluid dynamic and thermodynamic principles, problem specific computations can be performed. A very thorough book was found explaining many of these methods in depth

(Taler 2019). This book firstly explains the fundamental heat transfer theories including the mass, energy and momentum equations, and explanations of both laminar and turbulent fluid flow through ducts. In the next section the mathematical models are explained in detail. Regarding indirect heat exchangers, in the counterflow arrangement, the following equations models are of interest. All these formulae were verified through Cengel & Ghajar (2015), and found to be verified with different variables in some cases. When referencing temperatures in the formula below, refer to diagrams in figure 2-4.



Figure 2-4: Cocurrent flow (a) and Countercurrent flow (b) (Taler 2019).

Heat Transfer

Assuming that mass flow rates are constant, the outside is insulated and there are no external or internal heat sources there are two fundamental equations for the heat transfer:

$$\dot{Q}_h = \dot{m}_h c_h (T_{h1} - T_{h2})$$
$$\dot{Q}_c = \dot{m}_c c_c (T_{c1} - T_{c2})$$

This formula is showing that the heat transfer can be calculated from the mass flow rate, specific heat capacity and temperature difference from either the cold or hot fluid. Temperature lost from the hot fluid is gained by the cold fluid.

LMTD Method

The formula for finding the logarithmic mean temperature between the two fluids is fully derived in the source and can be shown as:

$$\Delta T_m = \frac{\Delta T_2 - \Delta T_1}{\ln\left(\frac{\Delta T_2}{\Delta T_1}\right)}$$

From this log mean temperature value, the heat transfer can be calculated using:

$$\dot{Q} = \Delta T_m A k_A$$

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where k_A is the overall heat transfer rate of the exchanger and A is the surface area of the transfer wall.

NTU Method

To calculate the NTU's, which are heat transfer units:

$$NTU = \frac{(k_A A)}{\dot{C}_{min}}$$

where C_{min} is the smaller of the two fluid's specific heat capacity rates. The specific capacity rates are the specific heat values multiplied by the mass flow rate.

 ε is the heat exchanger effectiveness and described as the ratio between the real thermal power and the maximum power from the exchanger:

$$\varepsilon = \frac{\dot{Q}_{rz}}{\dot{Q}_{max}} = \frac{\dot{Q}_{rz}}{\dot{C}_{min} \left(T_{h,wlot} - T_{c,wlot}\right)}$$

For counter-current flow heat exchangers, $T_{h,wlot} - T_{c,wlot} = T_{h1} - T_{c2}$ (Hot inlet – cold inlet)

Rearranging, the main equations used to find unknowns are:

$$\varepsilon = \frac{\dot{C}_h \left(T_{h1} - T_{h2}\right)}{\dot{C}_{min} \left(T_{h1} - T_{h2}\right)} = \frac{\dot{C}_c \left(T_{c1} - T_{c2}\right)}{\dot{C}_{min} \left(T_{c1} - T_{c2}\right)}$$
$$\varepsilon = \frac{1 - \exp\left[-NTU\left(1 - \frac{\dot{C}_{min}}{\dot{C}_{max}}\right)\right]}{1 - \frac{\dot{C}_{min}}{\dot{C}_{max}} \exp\left[-NTU\left(1 - \frac{\dot{C}_{min}}{\dot{C}_{max}}\right)\right]}$$

Temperature at a point

The temperature in the cold or hot fluid can be calculated at any distance along the heat exchanger using two equations:

$$T_{h} = T_{h1} - \frac{(T_{h1} - T_{c2})\{1 - \exp\left[-k_{A}U_{A}\left(\frac{1}{\dot{m}_{h}c_{h}} - \frac{1}{\dot{m}_{c}c_{c}}\right)x\right]\}}{1 - \frac{\dot{m}_{h}c_{h}}{\dot{m}_{c}c_{c}}\exp\left[-k_{A}A\left(\frac{1}{\dot{m}_{h}c_{h}} - \frac{1}{\dot{m}_{c}c_{c}}\right)\right]}$$
$$T_{c} = T_{h1} - \frac{(T_{h1} - T_{c2})\{1 - \frac{\dot{m}_{h}c_{h}}{\dot{m}_{c}c_{c}}\exp\left[-k_{A}U_{A}\left(\frac{1}{\dot{m}_{h}c_{h}} - \frac{1}{\dot{m}_{c}c_{c}}\right)x\right]\}}{1 - \frac{\dot{m}_{h}c_{h}}{\dot{m}_{c}c_{c}}\exp\left[-k_{A}A\left(\frac{1}{\dot{m}_{h}c_{h}} - \frac{1}{\dot{m}_{c}c_{c}}\right)x\right]\}}$$

Where x is the distance from the hot inlet, $\alpha_c \& \alpha_h$ are the heat transfer coefficients of the cold and hot fluids, and U_A is the transfer wall circumference.

2.4.2 Computation Fluid Dynamic (CFD) Modelling

A study by Sharifi et al (2018), used a computation fluid dynamic method to model the heat transfer improvements of a horizontal heat exchanger with helical wire inserts. These inserts produce a spiral flow

through the core improving efficiency. To confirm the accuracy of the model, Sharifi et al (2018) compared initial results with a previous study with numerical results. The software package "Fluent" was used for CFD computation. Sharifi et al used a highly refined mesh around the tube walls and wire areas with a course mesh through the rest of the domain. The resultant mesh densities tested were 400,000, 1,200,000, 2,000,000 and 3,200,000 elements.

A similar study by Rajeshkumar et al. (2021), created a CFD model in ANSYS to analyse the improvements of changing the geometry of a heat exchanger to have fins added. The model created in this article only included one fluid domain but shows the general setup of a heat exchanger fluid domain. The study showed how the results were interpreted to see the model was realistic. This model used over 3 million elements for the single domain.

To test if corregated tubing is more efficive in a douple pipe heat exchanger than a simple wall, a study was peformed by Bashtani & Esfahani (2019). This study created CFD models in ANSYS of a section of heat exchanger with both simple wall and corrigated wall. The same boundary conditions were used on both experiements and the results compared to each other. The SST turbulence model was used and mesh independence study was completed to ensure the results were valid. The results were also validated using mathematical models. An element count of 4,000,000 elements was required for the corregated model.

These studies show that CFD can be used to model heat exchangers though the studies references found good results with many more elements that the ANSYS student version have available.

2.4.3 Physical Experiments

There have been recent studies into heat exchanger performance using physical experiments, though none can be found in relations to the use of a valve in the entry region of the exchanger.

An experiment by Aghayari et al (2015), used an experimental jig, like the Armfield HT36, in a study to test the effects of nanoparticles within a fluid on the overall heat transfer. For this study a dual-wall exchanger was fabricated, and the experimental results considered applicable to plate style (and other) heat exchangers.

Amanowicz (2018), is another example of a great heat exchanger experiment where an experimental jig was created with various sensor test points to perform physical experiments. This study was performed on multichannel earth-air exhanger but showed very thorough physical and CFD testing.

A book by Fridman & Mahajan (2014), was studied as is discussed techniques to completed physcial experiements around heat exhangers in the virtual environment. It was noted in this book that they used the Armfield HT36 experiemental equipment which is the same equipment used in the USQ laboratory.

2.5 Heat Exchanger Entry Conditions

The primary focus of this dissertation is at the entry condition of the heat exchanger and how a control valve may affect the flow in this region. There does not seem to be any studies directly investigating this for simple dual-wall type heat exchangers.

An example of a study that focuses on a similar scenario is by Iqbal and Syed (2011), where different finnedtype heat exchanger in entry region geometry was investigated to find the best performing geometry. This study found that the different geometry and fin arrangements did produce different heat transfer rates in the entry region that fully developed flow areas. The study indicated the heat transfer rate could possibly be influenced by the valve causing a different effective geometry.

2.6 Control Valve Types

Heat exchanger control systems adjust the desired output temperature by using control valves on the process water side of the system. The common effective valve types used to regulate of the flow are (Kapustenko, et al 2009):

- Globe
- Angle
- Ball
- Plug
- Needle
- Butterfly.

The most effective of these is noted to be the globe or saddle valves, however due to their complexity and expense, butterfly valves were noted to be the most common control valve used in industry. With the Author's understanding of the industry, it is assumed butterfly valves will be used in our application.

A good resource explaining the differences in valve technologies and verifying that the butterfly design is ideal for control applications is the valve datasheet by Tomovalve (n.d.). This technical datasheet shows the different valve types and explains their strengths and weaknesses. The data sheet shows that each valve is sold with a known Cv value which specifies the relationship between the flow rate and pressure drop of a valve.

2.7 Butterfly Valve Modelling

Butterfly valves have been identified to be the most common valve type used in industry. Butterfly valves are a mechanical device used to restrict the flow of liquid through their cross-sectional area by rotation of a round disk. When rotated 90°, the valve is fully open, and the design offers very little restriction. When fully closed the disk seals on a sealing surface in the valve body allowing no flow of fluids (Song, Wang, Park 2009).



Figure 2-5: Butterfly valve simplified model and example from industry (Janusz 2006).

2.7.1 Mathematical Modelling

The Cv value of a valve is often provided with a valve in the form of a datasheet for example of the dataset provided by Sure Flow Equipment Inc in figure 2-7 below.

Cv Values - Valve Sizing Coefficients (US - GPM @ 1 PSI Δ P)									
Size	Flow in GPM @ 1 PSI Δ P @ Various Disc Angles							Full 90°	
	10°	20°	30°	40°	50°	60°	70°	80°	Open
2	0.1	5	12	24	45	64	90	125	115
2 1/2	0.2	8	20	37	65	98	144	204	196
3	0.3	12	22	39	70	116	183	275	302
4	0.5	17	36	78	139	230	364	546	600
5	0.8	29	61	133	237	392	620	930	1,022
6	2	45	95	205	366	605	958	1,437	1,579
8	3	89	188	408	727	1,202	1,903	2,854	3,136
10	4	151	320	694	1,237	2,047	3,240	4,859	5,340
12	5	234	495	1,072	1,911	3,162	5,005	7,507	8,250
14	6	338	715	1,549	2,761	4,568	7,230	10,844	11,917
16	8	464	983	2,130	3,797	6,282	9,942	14,913	16,388
18	11	615	1,302	2,822	5,028	8,320	13,168	19,752	21,705
20	14	791	1,674	3,628	6,465	10,698	16,931	25,396	27,908
24	22	1,222	2,587	5,605	9,989	16,528	26,157	39,236	43,116

Figure 2-6: Butterfly valve advertised Cv values.

These Cv value gives the ratio of the flow rate to the pressure drop across the valve at various valve angles. They are used by system designers to choose the appropriate valve for a particular application. This Cv value is an imperial ratio which has the equivalent metric ratio which is the Kv value. The relevant equations are:

$$K_V = Q \frac{\sqrt{SG}}{\Delta P}$$
$$K_V = 0.865 C_V$$

where K_V is the flow factor $(\frac{m^3}{h})$, Q is the flowrate $(\frac{m^3}{h})$,SG is the fluid's specific gravity and ΔP is the pressure difference in bar (Fisher 2001). These equations show that with a known valve, flow rate can be calculated if the pressure difference is known, or the pressure difference can be calculated if the flow rate is known. If the Cv value is not known, proper sizing of the valve can be calculated using (Song, Wang, Park 2009):

$$K_1 = \left(\frac{V_1^2}{2} + \frac{P_1 - P_2}{\rho}\right) * \frac{2}{v_2^2} - \left(1 + \frac{f * L}{D}\right)$$

where K_1 is the valve coefficient value provided by the manufacturer, P_1 and P_2 are the static pressures upstream and downstream of the valve, v_1 and v_2 are the upstream and downstream velocities, L is the distance between P_1 and P_2 , D is the hydraulic diameter of the valve and f is circular friction factor.

2.7.2 Computational Fluid Dynamic Modelling

In an article explaining the methods of optimisation of a butterfly valve (Song, Wang, Park 2009) a combination of FEA and CFD were performed on a valve. In this article, CFD was completed on a butterfly valve within a pipe domain to optimise the design a valve for optimal strength to weight ratio. Some parameters of note here were the upstream length of 8x the valve diameter and downstream length of 10x the valve diameter in respect to the valve.

Janusz and Czeslaw (2016), performed a physical and CFD experiment on butterfly valves to determine the flow characteristics, pattern and pressure changes caused by a butterfly valve in with water flow for both laminar and turbulent flows. The study reveals recirculation is non-existent at shallow valve angles behind the valve disk. Some parameters of note here were the upstream length of 2.5x the valve diameter and downstream length of 15.5x the valve diameter in respect to the valve.

A study by Del Toro, Johnson, and Spall (2015), performed a comprehensive dataset to measure the pressure drop, hydrodynamic torque, flow coefficient, loss coefficient, and torque coefficient on a specific valve under different opening angle positions. This study found that the CFD results varied from actual in the low and high angle cases. Physical experiments were conducted for the mid-open ranges of 30-60 degrees. The study concluded velocity and turbulence could create temperature differences within a heat exchanger.

It can be seen from these studies that the butterfly valve causes turbulence to the fluid around the valve and can affect the flow for some distance past the valve. In all cases the effect of the valve is seen to only influence the flow for a short distance. This aligns with general flow thermal entry lengths with are assumed to be 10D (Cengel & Ghajar 2015).

2.8 Turbulence Modelling

When fluid is travelling through the inside of a tube and reaches a certain speed relative to the fluid density and geometry of the tube, the flow will lose stability and transition to turbulent flow (Rao 2017).



Figure 2-7: Flow transition from laminar to turbulent flow (Rao 2017).

Turbulence produces less predictable and unstable velocities through the fluid including eddies. There are several models used within CFD software suited to modelling turbulent flow with the main two being variants (Wasserman 2016), of:

- Standard k-ε
- Standard k-
- SST k-**ω**.

There are more complex models, for example direct numerical simulation (DNS) available requiring much more computational power, however these three and variants of them are the most used (Andersson 2012). These models all use a method of simplifying the Reynolds averaged Navier stokes equations by assuming statistical averaging for unknown values. Some of the models work better for different applications due to the assumptions made.

k-ε Model

The standard k- ε model is the most widely used model and is computationally efficient (Andersson 2012). This model is strong for flows within pipes, however, has some weaknesses around the wall area. It is also known to be weak when simulating swirling flows, streamline curvature and axisymmetric jets. To improve on the standard model, RNG and realizable variants have been developed and commonly used in place of the standard model. The RNG variant was made to better model swirling type flow and the realizable model has been developed to handle cases with large mean strain rates. Near wall modelling effects can also be added to the k- ε model to improve performance of the standard k- ε wall modelling.

k-ω Model

The k- ω differs from the k- ε model in that it can manage wall boundary layers with high pressure gradients. This is particularly useful in the high flow near a wall – for example flow over a wing. A very fine mesh is required around the wall for this model. Variants of the k- ω also exist, however do not add value to this project, other than the SST variant discussed below.

SST Model

The SST model uses both the k- ϵ and k- ω model. It uses the k- ω close to the wall regions and transitions to the k- ϵ in regions of less shear stress (ANSYS 2009).

In the modelling of heat exchangers with control valves the choice of turbulence model to use is not clear. A recent study was found by Sung-Woong et al. (2021), compared three models with control valves of various diameters. This study found no conculusion in their attempt to define a best model for simulating the turbulence around a control valve. The study suggests all models should be tried and analysed case by case.

2.9 Similar CFP and Physical experimental Studies

In 2009 a study was completed by the National Technical University (Kharkiv Polytechnic Institute) to improve the flow quality of a butterfly valve (Kapustenko, et al 2009). In this study both computer and physical modelling were performed on a heat exchanger and butterfly valve system. The study found that they could

better control the temperature using the parametric predictive control technique with less oscillation and quicker response. These results are of little impact to this dissertation, but the methodology is of interest.

A study of a corrugated double pipe heat exchanger by Bashtani & Esfahani (2019), although not modelling butterfly valves, is a great example of where a CFD model was built and compared to a mathematical model, producing a very robust experiment.

In 2011, a study was completed by the Department of Chemical Engineering, Lehigh University (Luyben 2011), with physical experiments to test the design of heat exchanger system when bypassing is used. The results of this study found an increased area of the heat exchanger and more bypassing improves the ratio of maximum-to-design heat transfer rates. Bypassing is not an applicable option for our purpose as the two fluids used are different.

After extensive literature review no studies could be found investigating the influence of a butterfly control valve on the flow or heat distribution within a heat exchanger.

2.10 Knowledge Gap

There is a wealth of knowledge available on heat exchanger technologies, control valve technology, heat exchanger efficiency, control valve efficiency and modelling of these individual systems. Unfortunately, there are no studies on how the use of a control valve at the heat exchanger process water entry point would affect the heat exchanger performance compared to a heat exchanger using a variable speed control pump with a control valve.

It is hypothesized that the use of a control valve at the heat exchanger process water entry point could create turbulence and other entry conditions that could affect the heat distribution in the heat exchanger.

3.0 Chapter 3: Study Methodology

3.1 Experimental Methodology

The following step-wise phases were completed in succession and form the structure of this investigation. Completion of all phases is necessary before conclusions can be formulated:

Phase 1: Conduct physical experiments of a simple heat exchanger arrangement and gather experimental data

Phase 2: Undertake computational fluid dynamics (CFD) simulation of a heat exchanger modelled on the physical experiment

Phase 3: Compare the results of the experimental and simulation studies. Refine the CFD model until the results are within an acceptable error range

Phase 4: Conduct a physical experiment and CFD model of a simple heat exchanger using a control valve at the process water entry point and analyse the temperature distribution at a global level

Phase 5: Analyse the temperature distribution at the entry of the heat exchanger for localized hot spots on the transfer wall

Phase 6: Scale the CFD model to the size and boundary conditions of the real-life application and repeat global and localized analysis.

3.2 Limitations

3.2.1 Student

The limiting factor of this project is the student's time. The timeframe to complete the project was 7-8 months with the student completing this course part time alongside work and family commitments.

The student is an undergraduate and unfamiliar with ANSYS software, and CFD methodologies. The CFD course (MEC5100) was not available for undergraduate students and the student's electives have already been exhausted.

3.2.2 Heat Exchanger Technology

The large plate-type heat exchanger used in large dyno engine applications has driven the student's interest in this project. Modelling of this type of heat exchanger is more complex as the fluid may behave as though it were in an open channel. The complexity increases even more as it is likely to exceed limitations of the ANSYS student version.

A more detailed analysis could be performed using the actual geometry of an industrial plate-type exchanger; however, it would be unlikely that most manufactures' would share the detailed drawings of their heat exchanger parts to model in a CFD suite.

This study was completed on dual-tube type exchanger design and reveals the effects of a butterfly valve in the entry region considering global and local heat distribution. As discussed further in section 6, a study should be completed on a plate-type exchanger with appropriate geometry before making conclusions on the true industrial application.

3.2.3 ANSYS Student Edition

Experiments performed in the writing of this dissertation were performed on the ANSYS student edition which has mesh limitations of 512,000 elements. As discussed in the literature review, in section 2.4.2, similar available studies have required over 3 million elements. It is likely the results of this study could have errors due to these mesh element limits.

3.3 Scope

For this study, a dual-wall type exchanger will be used as this is the simplest exchanger that can be created within the computational and experimental environment available at the University of Southern Queensland Toowoomba campus laboratory.

3.4 Methodology Used and Expected Outcomes

It is hypothesized that the use of a control valve at the heat exchanger process water entry point could create turbulence and other undesirable entry conditions affecting the global and local entry region transfer wall heat distribution within the heat exchanger. It is not possible to measure the temperature distribution through the entry region of the heat exchanger accurately, or completely, under the conditions of this physical experiment as the flow turbulence is very complex and any physical measurement devices will affect the flow of water in this area. Computational Fluid Dynamic (CFD) modelling will be the primary method used to analyse this the fluid behaviour.

The CFD models will be validated with physical and mathematical where possible before conclusions are formulated.

It is expected the modelling will show no significant global change in heat exchanger performance, with or without a valve. However, it is anticipated the modelling will show significant local temperature distribution difference due to turbulence created from the valve.

3.5 Study Planning/Timeline

A project plan was initially completed with various key components timelines and milestone key dates and can be seen in appendix B. The scope has changed with the initial literature review and experimental data and a summary of the adjusted major project milestones can be seen in table 3-1 below:
Table 3-1: Major project milestones.

Item	Original Due	Actual	Notes
	Date	Completion Date	
Literature Review	30 Apr 2021	08-Aug-2021	Timeline priority changed to the ANSYS learning and experimental work to ensure risk mitigated as shown in section 3.7. Completed 50% by May, remainder in Aug.
Research HT36 Jig	30 Apr 2021	13 Apr 2021	
Complete initial CFD Model	30 Apr 2021	30 Apr 2021	
Complete initial physical experiment	25 Jun 2021	24 May 2021	
Compare results and optimise CFD	10 Jul 2021	25 May 2021	
Compile and lodge progress report	26 May 2021	26 May 2021	
Complete CFD and physical experiment with valve entry condition.	N/A	18 Jul 2021	Was not in initial scope but critical to find results to meet aim. New Goal 15-Jul-2021
Scale CFD models to real-life boundary conditions	21 Aug 2021	01 Sep 2021	
Analyse data and generate conclusions	01 Sep 2021	05 Sep 2021	
Compile and lodge partial dissertation	08 Sep 2021	07 Sep 2021	
Compile and present presentation	24 Sep 2021	23 Sep 2021	
Compile and lodge final dissertation	13 Oct 2021	13 Oct 2021	

3.6 Resource Planning

The planning of this project identified several items of equipment that would be required to complete the experiments and perform the analysis required to meet the objectives of this dissertation.

3.6.1 Physical Experimental Jig

The University of Southern Queensland has an experimental heat exchanger used for educational purposes. Access to this equipment was required to establish baseline data for comparison to computational models. Access to the USQ laboratory and technical staff was negotiated with the project supervisor.

The equipment which the student required access to was, the Armfield HT36 heat exchanger and computer program located in the Toowoomba campus Z-block. All experiments within the scope of this project were completed without purchasing additional equipment by the University or the student.

3.6.2 Software

Various software applications were required to complete the analytical computations and compile the dissertation report. Modelling was performed on a combination of the student's personal computer and USQ computer lab resources. The software used were:

- Microsoft Office package
- ANSYS 2021 R1 Student version
- ANSYS 2020 R2 Student version

3.6.3 Computer Lab Access

Computational modelling required access to the USQ computer laboratories to gain increased processing ability.

3.6.4 Confidentiality of Proprietary Information

On initial launch of the study, it was thought that proprietary information might be needed to accurately model scenarios, however it was found all the required information to get acceptable results was publicly available. This negated the need to include confidentiality restrictions to this dissertation.

Armfield HT36 Test Equipment

To accurately model the Armfield HT36 test equipment, correct dimensions and material properties were required. The student was able to source this information through combining information from the Armfield instruction booklet with actual measurements of components.

Application Heat Data

The heat generation and operating temperatures of an industrial High Horse-power engine was found publicly available through search engine search. The information was found to be sufficient to scale the model to represent an industrial application.

3.7 Project Risk

Risks to the success of this project were identified and documented. A simple risk matrix was developed as seen in figure 3-2 below. Where possible, controls were put in place to lower the risk as much as possible. As seen in the table the biggest risk to the success of the dissertation is other commitments in the student's life, including work and family. The author's work stretched to many hours of over-time implementing a new Manufacturing Execution System (MES) where he was the main resource. Item 6 also proved true as the author spent a few key study weekends in hospital with my young baby. Planning, mitigating the risk and getting ahead of deadlines allowed this dissertation to be completed by the deadlines required.

ID #	Description of Risk	Likelihood	Consequence	Risk Score	Controls	Residual Risk
1	File corruption / Data loss	Unlikely	Extreme	High	- Save file on OneDrive for cloud backup. - Regular Manual Backup of Files on cloud and USB stick	Low
2	Scope Creep	Likely	Medium	Medium	 Stick to Project Specification and discuss with Supervisor if project creep is identified. 	Low
3	Physical Experiment Equipment Failure	Unlikely	Medium	Low	- Perform physical experiment as earlier as possible in case alternate options need pursuing	Low
4	Software/Hardware Failure	Unlikely	Medium	Low	 Backup software is available on the Student's work computer as well as University Labs. Ensure money available if required to replace failed student hardware 	Low
5	Lack of time to complete dissertation - work commitments	Likely	Medium	Medium	- Discuss with work, keep annual leave available in case required. - Ensure significant progress so unplanned unavailability will not leave in Failing position	Medium
6	Lack of time to complete dissertation - family and personal health/commitments	Likely	Medium	Medium	- Leverage assistance with family to look after child during wife's nursing placement periods - Ensure significant progress so unplanned unavailability will not leave in Failing position	Medium
7	Unable to continue dissertation due to lack of available information	Unlikely	Low	Low	- Complete literature review as soon as possible and discuss with sponsor.	Low

Figure 3-1: Project risk matrix.

4.0 Chapter 4: Physical and Computer Modelling

4.1 Phase 1: Verification Physical Modelling

The test equipment being modelled in the physical experiments to validate the computational model is the Armfield HT36 Extended Tubular Head Exchanger located in the University of Southern Queensland Toowoomba campus.



Figure 4-1: Armfield HT36 extended heat exchanger experiment in USQ laboratory.

4.1.1 Experiment Equipment

The Armfield HT36 heat exchanger was built to support educational courses. The system contains four major sub-systems as well as auxiliary plumbing not described:

- Heat Exchanger Core
- Control System
- Heating System
- Computer System.

Heat Exchanger System

The heat exchanger core comprises four dual tube lengths with the internal walls of 0.6mm stainless steel. The core of the system has ten thermocouples throughout to measure and record the temperature at various points through both the hot and cold sections of the exchanger.

Control System

The control system comprises a serious of valves allowing switching between parallel and counter-flow. It has control valves enabling adjustment of the fluid flow throughout circuits. Valves are also included to isolate lengths of the heat exchanger core so that experiments can be performed on one, two, three or four lengths. The valves used to change the direction of flow and tube lengths are manually controlled however the flow rates are controlled through a computerised control system.

Heating System

The heating system can control the temperature of the hot circuit simulating a heat source in industry. The temperature is set on the Armfield software, and a heater/thermocouple is used to maintain a consistent hot water temperature. The heating system also contains a fluid sensor, so the pump does not run dry.

Computer System

The computer software and hardware controls the flow rate valves and monitors/records the temperatures in the ten (10) thermocouples. The computer can control the control system by the changing PID controller parameters.

4.1.2 Design of Experiment

The experiment performed for validation of the ANSYS model was in accordance with the Armfield HT36 Instruction Manual Issue 7 (Armfield 2014). The test equipment was set up in counter-flow arrangement using all four (4) tubes. Once turned on, hot water was allowed to heat and circulate to purge air bubbles. The coldwater side was also allowed to flow and clear out any air bubbles.

Once setup was completed, the entry conditions were set to pre-determined flow rates and temperatures given in the manual as can be seen in table 4-1 below. The flow rates and temperatures throughout the experimental rig are logged using the Armfield HT36 software. These logs were exported for data analysis and comparison to the ANSYS model.

Two tests with varying test conditions were completed and compared with two CFD models. This was done over a single experiment to increase confidence the ANSYS modelling matches the physical experiment. A single experiment could be likely modelled to match, however, the second data point verified the model with more confidence.

Test Case	Parameter	Value
	Hot Water In	30°C above cold water temperature
1	Hot Water Flow	3 lpm
	Cold Water In	Temperature of the tap water
	Cold Water Flow	1 lpm
	Hot Water In	30°C above cold water temperature
2	Hot Water Flow	3 lpm
-	Cold Water In	Temperature of the tap water
	Cold Water Flow	2 lpm

Table 4-1: Physical experiment test conditions.

4.1.3 Experimental HSE Risk

This experiment comes with risk to the student and possibly other bystanders. A risk assessment was performed, and controls put in place, until all risks were as low as reasonably possible. With all the identified controls implemented, all risks were classed as 'low'. The risk assessment was then approved by the supervising staff. The full risk assessment can be seen in appendix C.

A site safety induction was completed on the day of the experiment to make the student aware of local layout, staff, procedures, and equipment.

4.1.4 Experiment Details

The experiment was performed in the University of Southern Queensland labs on the morning of 24th of May 2021. The ambient temperature was 17°C during the experiment. The experiments were undertaken and in accordance with procedures other than the following:

- The heating elements were not able to reach the inputted temperature (48.6° C) when the cold-water flow rate was set at 2 lpm. The values were recorded and will still be suitable for validation purposes. These can be seen in the T1 values in table 4-3 below
- Readings were not as stable as expected, however several data points were captured for each experiment to enable averaging of the values

The full set of results can be seen in table 4-2 and table 4-3 below.

4.1.5 Results

<i>Table 4-2:</i>	Table	of resul	ts from	experiment	1.
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Sample Number	Elapsed Time [mm:ss]	Temp T1 [°C]	Temp T2 [°C]	Temp T3 [°C]	Temp T4 [°C]	Temp T5 [°C]	Temp T6 [°C]	Temp T7 [°C]	Temp T8 [°C]	Temp T9 [°C]	Temp T10 [°C]	Hot Water Pump Setting [%]	Hot Water Flowrate Fhot [l/min]	Cold Water Valve Setting [%]	Cold Water Flowrate Fcold [l/min]	Flow Orientation
1	00:01	48.4	47.0	44.9	43.3	41.3	18.5	24.0	27.8	32.2	35.4	46	3.1	53	1.04	Countercurrent
2	00:06	48.4	47.0	44.9	43.2	41.4	18.5	23.9	27.8	32.0	35.3	46	3.1	53	1.01	Countercurrent
3	00:11	48.4	46.9	44.8	43.2	41.3	18.5	24.0	27.4	32.2	35.4	46	3.0	53	0.92	Countercurrent
4	00:16	48.5	47.0	44.9	43.2	41.3	18.5	23.8	28.0	32.3	35.5	46	3.0	53	0.99	Countercurrent
5	00:20	48.6	47.0	44.9	43.3	41.4	18.5	24.0	28.0	32.0	35.5	46	3.0	53	1.06	Countercurrent
6	00:25	48.6	47.0	44.8	43.2	41.5	18.5	23.9	27.9	32.2	35.3	46	3.1	53	0.98	Countercurrent
7	00:30	48.6	47.1	44.9	43.2	41.5	18.5	23.9	28.0	32.1	35.6	46	3.0	53	0.95	Countercurrent
8	00:35	48.7	47.2	45.2	43.3	41.4	18.5	24.0	27.9	32.1	35.5	46	3.0	53	1.03	Countercurrent
9	00:40	48.6	47.1	45.1	43.5	41.5	18.5	23.8	27.6	32.3	35.6	46	3.0	53	0.94	Countercurrent

Table 4-3: Table of results from experiment 2.

Sample Number	Elapsed Time [mm:ss]	Temp T1 [°C]	Temp T2 [°C]	Temp T3 [°C]	Temp T4 [°C]	Temp T5 [°C]	Temp T6 [°C]	Temp T7 [°C]	Temp T8 [°C]	Temp T9 [°C]	Temp T10 [°C]	Hot Water Pump Setting [%]	Hot Water Flowrate Fhot [l/min]	Cold Water Valve Setting [%]	Cold Water Flowrate Fcold [l/min]	Flow Orientation
1	00:00	44.0	42.2	39.7	37.7	35.7	18.6	22.1	24.9	28.2	30.6	46	3.0	100	1.83	Countercurrent
2	00:05	44.0	42.2	39.8	37.7	35.7	18.6	22.1	24.9	28.1	30.6	47	2.6	100	1.87	Countercurrent
3	00:10	44.1	42.2	39.8	37.7	35.6	18.6	22.1	24.9	28.1	30.5	47	3.1	100	1.86	Countercurrent
4	00:15	44.0	42.2	39.9	37.9	35.7	18.6	22.1	25.0	28.1	30.6	46	3.1	100	1.83	Countercurrent
5	00:20	43.8	42.0	39.6	37.5	35.5	18.6	22.1	24.9	28.0	30.4	47	3.0	100	2.04	Countercurrent
6	00:25	43.9	42.0	39.5	37.5	35.5	18.6	22.1	24.9	28.0	30.4	46	3.0	100	1.97	Countercurrent
7	00:30	43.7	41.8	39.5	37.5	35.5	18.6	22.1	24.8	28.0	30.3	46	3.1	100	1.97	Countercurrent
8	00:36	43.4	41.6	39.1	37.3	35.3	18.6	22.0	24.8	27.9	30.2	46	2.9	100	1.93	Countercurrent
9	00:41	43.3	41.5	39.2	37.2	35.2	18.6	22.0	24.7	27.8	30.2	46	2.9	100	1.89	Countercurrent

These values were averaged and plotted to visualise the data as seen in figure 4-2 and 4-3 below. The curves are the temperature distributions expected with counter-flow heat exchangers.



Figure 4-2: Hot and cold-water measurements with hot water 31pm and cold water 11pm flow rate.



Figure 4-3: Hot and cold-water measurements with hot water 31pm and cold water 21pm flow rate.

4.2 Phase 2: Verification ANSYS Modelling

The test equipment being modelled in the CFD model is the Armfield HT36 Extended Tubular Head Exchanger, identical as used in section 4.1.



Figure 4-4: Armfield HT36 extended heat exchanger (Armfield 2015).

To create the 3D model, the available information was used from the supplier manual (Armfield Ltd). Where data was not available, the test rig was reversed engineered, and measurements taken. Information gathered from the supplier identified the inner tube was 3/8" stainless steel tube with 0.6mm wall thickness and length of 760mm. The outer tube is 16mm acrylic tube with 2mm wall thickness and length of 670mm. This gives a nominal OD of the annulus fluid 14mm cross section and a nominal OD of the inner tube as 8.925mm.

4.2.1 Assumptions Made

Base and Stand

The Armfield HT36 is mounted on a stand which holds the experimental hardware in place. The stand does not affect the experiment and has been omitted in the 3D model

'O'-Ring Seals

The Armfield HT36 is designed with 'o'-ring seals to allow for expansion and contraction of the joints. The model does not simulate this behaviour and assumes a simplified solid sized joint.

The Armfield HT36 uses 3/8" push connect fittings. These fittings are not required for modelling and the model was simplified with solid size on size joints assuming the fluid flows through a continual 9.825mm cross section. The elbow is simplified as a 15mm radius.

The elbow fittings, large 'tee' unions and thermocouple adapter 'tee' unions are noted to be made of acrylic material and considered to be adiabatic.

The outer annulus of the heat exchanger is manufactured from acrylic material and considered to be adiabatic.

In between the acrylic fittings each end connection has sections of 3/8" stainless steel exposed to the air. Heat loss through these joints cannot be ignored and are included in the CFD model. Where the tube is offset as shown in the "Jumper Tube" callout in figure 4-5 below, is it simplified in the model to be symmetric with equal halves of the total tube length either side of the thermocouple.



Figure 4-5: Photo and nomenclature of Armfield HT36 heat exchanger end transfer arrangement.

Layout

The actual experimental device is laid out such that it takes as little bench space as possible. Our model however assumes a flat orientation and was chosen because it will not affect the results of the experiment, however, will present that data in a neater way. This layout is like the flow diagrams from the Armfield Teaching Extracts Manual shown in figure 4-6.



Figure 4-6: Counter-current flow diagram (Armfield 2015).

4.2.2 Model Creation

The 3D model of the fluid path was created in ANSYS DesignModeler using a combination of extruded and swept frozen volumes. Booleans were then created removing the hot section volume from the cold section volume. No physical wall was modelled between the two fluid domains, instead the Fluent "shell conduction" mode was used alongside zero-transfer wall boundary conditions.

Segments in the sweep path were made to create segments for applying boundary conditions for areas where stainless steel were exposed to the air. These locations will have heat loss from convection and were modelled accordingly.



Figure 4-7: The Armfield HT36 fluid path 3D model.



Figure 4-8: Segments for heat loss through convection.

Meshing

To setup the initial model a mesh size was chosen to achieve as accurate results as possible, whilst staying within the limits of ANSYS Student version which is limited to 512,000 elements. Once a working model was produced a mesh analysis was completed to find an appropriate mesh size to achieve accurate results whilst minimizing the calculations required.

A combination of different meshes were chosen to achieve accuracy in the complex areas of geometry whilst keeping mesh in the simpler regions less dense. Whilst the element limit is 512,000, ANSYS was found to require a lower limit of about 450,000, otherwise it failed during the Fluent modelling stage with an element limit warning. This was likely due to the use of the "shell conduction" feature for the transfer and convection walls as Fluent will automatically create a layer of elements for the wall calculations.

Hot water domain: The hot water domain has a very simple geometry; it mainly comprises a straight pipe with simple radius bends on the ends. A sweep mesh method was chosen as it gave the best shaped mesh for accuracy around the transfer wall whilst giving neat mesh on the corners. For this domain, the following mesh parameters were used:

- Method: Sweep mesh, using hot water entry face as source and outlet as the target
- Mesh Type: All Quad
- **Divisions:** 2200
- Edge Divisions: 28
- Bias: No Bias.

Cold Water Domain: The cold-water domain has a more complex geometry with sharp corners between the transfer ends. To get accurate results whilst minimizing the elements used, the mesh around the corners was refined whilst keeping the linear areas relatively coarse. For this domain, the following mesh parameters were used:

- Method: Tetrahedrons
- Body Sizing: 0.0026m
- Face Sizing: Around the corner areas 0.0008.

The total elements with this setup equates to 443,487 elements. A graphical representation of the resulting mesh can be seen in figure 4-9 and 4-10 below.



Figure 4-9: Resulting mesh for initial verification.



Figure 4-10: Resulting mesh for initial verification – sectioned through the centre of cold-water corner.

Governing Equations

The Fluent software was chosen to perform the calculations and three fundamental equations will be solved across the system:

Continuity Equation (conservation of mass) (Pedlosky 1987):

$$\frac{\partial \rho}{\partial t} + \nabla(\rho, \boldsymbol{u}) = 0$$

Which in our case of incompressible fluid, can be simplified as:

$$\nabla \mathbf{u} = 0$$

Momentum Equation (Sharifi et al 2018):

$$\frac{\partial}{\partial t}(\rho, \boldsymbol{u}) + \nabla(\rho, \boldsymbol{u}, \boldsymbol{u}) = -\nabla p + \rho, g + \vec{f}$$

Energy Equation (Sharifi et al 2018):

$$\frac{\partial}{\partial t}(\rho, e) + \nabla[(\rho, e + p) \boldsymbol{u}] = \nabla \left(k_{eff} \nabla T - \sum h_j \cdot \vec{J}_j + (\bar{\tau}_{eff} \cdot \boldsymbol{u}) \right)$$

Where ρ is the mass density, T is time, e is the energy per unit mass, p is the fluid pressure, k_{eff} is the thermal conductivity, h_j is the enthalpy of species j, J_j is the diffusion flux of species j, $\bar{\tau}_{eff}$ is the stress tensor, **u** is flow velocity vector and \vec{f} is the volumetric force.

Setup

Named Selections: All the key bodies, faces and walls were named so the correct boundary conditions and material properties could be added in the Fluent setup.



Figure 4-11: Model naming – Thermocouple location and hot water domain.

		Insulated Wall old Water Domain			
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Figure 4-12: Model naming – Cold water domain and insulated wall.



Figure 4-13: Model naming – Convection wall and Transfer wall

Material Properties

Material properties required were sourced from several locations for use in the CFD model as shown in table 4-4 below.

Material	Density	Specific	Thermal	Viscosity	Heat	Source
	(kg/m^3)	Heat	Conducti	(kg/(m s)	Transfer	
		(J/(kg K)	vity		Coefficient	
			(W/(m K)		(W/m^2.K)	
Water @	008.2	/182	0.6	0.001003	N/A	ANSVS Library
20°C	990.2	4102	0.0	0.001005		ANS IS LIDIALY
Stainless	7000	177	14.0	NI/A	N/A	(Cengel & Ghajar
Steel	7900	477	14.9			2015)
Insulation						(Dielectric
(acrylic)	1410	1395	0.2	N/A	N/A	Manufacturing 2020) /
						(Energy Education 2020)
Still Air	N/A	N/A	N/A	N/A	25	

Boundary Conditions

To be able to validate the physical experimental data to the ANSYS model, the CFD model was setup with boundary conditions matching those recorded from the physical experiment in section 4.1.

Test Case	Parameter	Value			
	Hot Water In	48.53°C = 321.53 K			
	Hot Water Flow	3.02 lpm			
	Hot Water Mass Flow (calculated)	0.05024 kg/s			
	Hot Water Volumetric Flow Rate (calculated)	5e-5 m^3/s			
1	Cold Water In	18.59°C = 291.59 K			
	Cold Water Out	0.99 lpm			
	Cold Water Mass Flow (calculated)	0.01647 kg/s			
	Cold Water Volumetric Flow Rate (calculated)	1.667e-5 m^3/s			
	Ambient Temperature	$17^{\circ}C = 290 \text{ K}$			
	Hot Water In	43.80°C = 316.8 K			
	Hot Water Flow	2.96 lpm			
	Hot Water Mass Flow (calculated)	0.04924 kg/s			
	Hot Water Volumetric Flow Rate (calculated)	5e-5 m^3/s			
2	Cold Water In	18.59°C =291.95 K			
	Cold Water Out	1.91 lpm			
	Cold Water Mass Flow (calculated)	0.03178 kg/s			
	Cold Water Volumetric Flow Rate (calculated)	3.333e-5 m^3/s			
	Ambient Temperature	17°C = 290 K			

Table 4-5: ANSYS verification model boundary conditions.

Laminar vs Turbulent Flow Model

Flow could be either laminar or turbulent depending on the speeds of the flow and the area through which the flow is passing, and this affects the choice of modelling processes in ANSYS Fluent. To determine if the flow is turbulent or laminar the Reynolds number will be calculated:

For Flow in a pipe:

$$Re = \frac{\rho Q D_H}{\mu A}$$

Where,

 D_H is the hydraulic diameter of the pipe (ID) (m)

Q is the volumetric flow rate (m³/s)

 ρ is the density of the fluid (kg/m^2)

 μ is the viscosity of the fluid kg/(m.s)

A is the cross-sectional area (m^2)

In the case of an annulus the hydraulic diameter becomes the difference between the hole diameter (ID of outside tube) and the pipe diameter (OD of the internal tube) (Ramsey 2019).

Viscosity of a fluid changes with temperature, therefore:

$$\mu_{inner} = 0.547 * 10^{-3}$$
 (water @50°C, Table A-15 (Cengel, Turner, Cimbala 2016))
 $\mu_{outer} = 1.002 * 10^{-3}$ (water @20°C, Table A-15 (Cengel, Turner, Cimbala 2016))

To find the Areas:

$$A_{inner} = \frac{\pi * D^2}{4} = \frac{\pi * 0.008925^2}{4} = 62.6 * 10^{-6} m^2$$
$$A_{outer} = \frac{\pi * D_{hole}^2}{4} - \frac{\pi * D_{pipe}^2}{4} = \frac{\pi * 0.014^2}{4} - \frac{\pi * 0.008925^2}{4} = 91.4 * 10^{-6} m^2$$

To simply for this case with known constants:

$$Re = \frac{\rho Q D_H}{\mu A}$$

$$Re_{inner} = \frac{998.2 * 8.925 * 10^{-3} * Q}{0.547 * 10^{-3} * 62.6 * 10^{-6}}$$
$$Re_{inner} = 260 * 10^{6} * Q$$

 $Re = \frac{\rho Q D_H}{\mu A}$

$$Re_{outer} = \frac{998.2 * (14 - 8.925) * 10^{-3} * Q}{0.001002 * 91.4 * 10^{-6}}$$
$$Re_{outer} = 55.3 * 10^{6} * Q$$

Inputting known flow rates:

Test Case 1:

 $Re_{inner} = 260 * 10^{6} * 5 * 10^{-5} = 13000$ $Re_{outer} = 55.3 * 10^{6} * 1.667 * 10^{-5} = 922$

Test Case 2:

 $Re_{inner} = 260 * 10^{6} * 5 * 10^{-5} = 13000$ $Re_{outer} = 33.5 * 10^{6} * 3.333 * 10^{-5} = 1843$

Rao (2017), states "For water the flow is laminar when R < 2300, transient when 2300 < R < 4000 and turbulent when R > 4000". Since our hot water path (inner tube) has Reynolds values >2000, the flow can be considered fully turbulent and appropriate turbulent modelling mode will have to be used. This is also appropriate due to the complex and sharp bends required in cold water pipe.

Because of turbulence the k- ε model was chosen for the initial modelling as it best suits internal flow as shown in section 2.5.3. Wall treatment was enhanced using the ANSYS option of 'Realisable' and 'Enhanced Wall Treatment' to better model the flow near the walls where the heat transfer will occur. This is suitable for the global model, however alternative methods will be tested during the modelling of the entry region with the valve in section 4.5 and section 5.

Fluent Setup Parameters

The following settings were configured in the Fluent Setup. Parameters not mentioned have been left as the Fluent 2021 R1 student version default values.

	Table 4-6: ANSYS	verification mode	el Fluent parameter	r setup
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Area	Parameter	Comments
Setup - Models	Energy Equation	Turned on
		k-epsilon
Setup - Models	Viscous Model	Realizable
		Enhanced Wall Treatment
Setup - Materials	Fluids	Water-liquid setup
Sotup Matorials	Solida	Steel-stainless setup
Setup - Materials	Solids	Acrylic setup
Setup - Cell Zone	Cold water domain	Setup as fluid water liquid
Conditions	Hot water domain	Setup as nuid – water-nquid
Setup - Boundary	T5 – Hot water out	Setup as mass flow outlet with flow
Conditions	$T_{10} = Cold$ water out	rate matched to the inlet. Pressure
Conditions		outlet was tested with same results
		Setup as mass flow inlet
Setup - Boundary	T1 – Hot water in	Setup flow rate as normal to
Conditions	T6 cold water in	boundary with flow rate and
Conditions		temperature as per actual results in
		4.1.5
Setup - Boundary	Insulated Wall – Cold water domain	Setup heat transfer coefficient to 0
Conditions	Insulated Wall – Hot water domain	Setup heat transfer coefficient to o
		Setup convection heat transfer with
Setup - Boundary		stainless steel material value and
Conditions	Convection wall	single layer shell conduction of
Conditions		thickness 0.0006m, ambient
		temperature of 300K
		Setup as coupled transfer with the
Satur Boundary		shadow equivalent. Setup as single
Conditions	Transfer wall	layer steel-stainless shell
Conditions		conduction with wall thickness of
		0.0006m
Solution - Method	Scheme	Coupled
Solution - Monitors	Residuals	All changed to 1E-06
Solution - Initialization	Method	Hybrid Initialization
Run Calculation	Number of Iterations	500

4.2.3 Results

Convergence of Calculations

After 500 iterations, the approximate average residual values were obtained:

- X, Y Velocities: 5e-6
- Z velocity: 6e-6
- Continuity equation: 2E-3
- Energy equation: 1.4E-7
- Epsilon: 2.3e-5
- k: 8.5e-6.



Figure 4-14: Residuals of test case 1.



Figure 4-15: Residuals of test case 2.

Temperature distribution values

The temperature distribution values were extracted from ANSYS Results model as shown in table 4-22. The temperatures at each location were calculated using a function of Mass Flow Average across a cross-sectional cut.

Test Case	Parameter	Result		
	T1 (Hot In)	321.53 K		
	T2 (Hot – bend 1)	320.46 K		
	T3 (Hot – bend 2)	318.93 K		
	T4 (Hot – bend 3)	316.85 K		
1	T5 (Hot Out)	313.90 K		
1	T6 (Cold In)	291.53 K		
	T7 (Cold – bend 3)	300.05 K		
	T8 (Cold – bend 2)	306.53 K		
	T9 (Cold – bend 1)	311.30 K		
	T10 (Cold Out)	314.84 K		
	T1 (Hot In)	316.80 K		
	T2 (Hot – bend 1)	314.89 K		
	T3 (Hot – bend 2)	312.68 K		
	T4 (Hot – bend 3)	310.22 K		
2	T5 (Hot Out)	307.38 K		
-	T6 (Cold In)	291.95 K		
	T7 (Cold – bend 3)	295.67 K		
	T8 (Cold – bend 2)	299.53 K		
	T9 (Cold – bend 1)	302.99 K		
	T10 (Cold Out)	306.17 K		

 Table 4-7: Temperature distribution reported at fixed locations throughout the heat exchanger.

Mass flow rate

To validate there are no problems with modelling, mass flow at the outlets was checked against the mass flow at the inlets as shown in figure 4-16 and 4-17. The change in mass was negligible in both cases.

[kg/s]	Mass Flow Rate
-0.01664 0.04991 -0.04991 0.01664	tl0_cold_out tl_hot_in t5_hot_out t6_cold_in
-1.3877788e-17	Net

Figure 4-16: Mass flow rate at inlet and outlet for Test Case 1.

Mass Flow Rate	[kg/s]
tl0_cold_out tl_hot_in t5_hot_out t6_cold_in	-0.03327 0.04991 -0.04991 0.03327
Net	2.7755576e-17

Figure 4-17: Mass flow rate at inlet and outlet for Test Case 2.

Temperature Distribution Contours

A plane cut was made through the X-Z axis, and a temperature contour plot made as shown in figure 4-18 and 4-19. The temperature contours show the continual cooling of the hot water and heating of the cold water as would be expected to be seen in this arrangement. The contour was inspected for any unintentional mixing of the two fluids or any other unusual or unexpected results.



Figure 4-18: Temperature contour through the X-Z plane for Test Case 1.



Figure 4-19: Temperature contour through the X-Z plane for Test Case 2.

4.2.4 Mesh Independence Study

A mesh independence study was performed to ensure that the results being obtained were stable and correct. Many computations were completed to find a mesh size suitable to achieve accurate calculations whilst minimizing computation time to complete the study. This mesh study was important to reduce calculation times for the bulk computations required in the rest of the dissertation. This study has required additional mesh elements for the modelling of the butterfly valve entry conditions in section 4.4, so minimising elements used that this stage if important to free these elements up.

To complete this study, 16 fluent simulations were run with various mesh sizing and the results tabulated. For the mesh independency study, an ideal set of boundary conditions, as shown in table 4-8 were used, and results compared to check what mesh setup obtained accurate results.

Test Case	Parameter	Value
	Hot Water In	$50^{\circ}C = 323 \text{ K}$
	Hot Water Flow	3.00 lpm
	Hot Water Mass Flow (calculated)	0.04991 kg/s
Mesh Study	Cold Water In	$20^{\circ}C = 293 \text{ K}$
	Cold Water Out	1.00 lpm
	Cold Water Mass Flow (calculated)	0.01664 kg/s
	Ambient Temperature	$20^{\circ}C = 293 \text{ K}$

Table 4-8: Ideal boundary conditions for mesh independence study.

Five resulting categories were reviewed and compared.

- Convergence Error Representation: Each study was compared to the baseline for the X,Y&Z velocity, continuity equation and energy equation residuals. To compare to the baseline, any value larger than the baseline was averaged and compared to the baseline in percentage error
- Temperature Error: Each study was compared to the baseline for the outlet and mid-core temperatures. Any deviation from the baseline was averaged across the four temperatures and compared to the baseline as an average
- Wall Pressure: The wall pressure in the centre of the core was compared to the baseline as a percentage error
- Mass Flow Rate: Each study was compared to the baseline for the outlet and mid-core mass flow rates. Any deviation from the baseline was compared to the baseline as percentage error
- Element Reduction: Each study was compared to the based for the total elements generated through the mesh setup. The mesh was compared to the baseline using a percentage.

The full results of the mesh independence study can be found in Appendix D. The resulting elements were plotted against the dependant variables to determine if the study was mesh dependant. Analysis of the results

in figure 4-20 below shows that the results are mesh dependant and stability is achieved with a mesh count of approximately 275,000 elements.



Figure 4-20: Mesh Independence Study results showing stability after approximately 275,000 elements.

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The study found the optimal settings for the mesh to minimize elements whilst reducing the temperature error, pressure error and residuals are:

- Hot Water Sweep Divisions: 1700
- Hot Water Edge Divisions: 22
- Cold Water Body Sizing: 0.0035m
- Cold Water Corner Face Sizing: 0.0015m
- Cold Water Transfer Face Sizing: 0.0025m.

This setup resulted in:

- Reduction of elements of 32% from 443,487 to 300,306
- Residual increase of 9% from the baseline
- Temperature difference of 0.04% from the baseline
- Mass flow difference of 0.26% from the baseline
- Pressure difference of 6.15% from the baseline.

4.3 Phase 3: Verify and Optimize the Model

To validate the CFD model, the temperature distribution across the thermocouple locations in the physical and computational models was compared.

4.3.1 Expected Errors

It is expected the physical and CFD results will have some level of error due to:

- Material property assumptions
- Geometry differences due to simplifications
- Acrylic not being truly adiabatic like modelled
- Accuracy and calibration of thermocouples
- Accuracy and calibration of the flow meters
- The turbulence model k- ε was used though some of the flow regions have laminar flow.

The flow meter used on the Armfield HT36 is the Sensata UF25B Ultrasonic Flow Meter which has an accuracy of $\pm 3\%$ of the reading when used in the range of the experiments performed (Sensata 2021). The thermocouples used on the Armfield HT36 were noted to be K-type thermocouples. The accuracy of K-type thermocouples are generally accepted to be ± 2.2 °C which is about $\pm 5\%$ in the range we are measuring.

4.3.2 Results

The physical vs CFD results for both flow rate experiments were tabulated and compared as shown in table 4-9 below.

Comparison o modelling a	f Physical and CFD after optimisation	Hot Water Flowrate Fhot [l/min]	Cold Water Flowrate Fcold [l/min]	Temp T1 [°C]	Temp T2 [°C]	Temp T3 [°C]	Temp T4 [°C]	Temp T5 [°C]	Temp T6 [°C]	Temp T7 [°C]	Тетр Т8 [°С]	Temp T9 [°C]	Temp T10 [°C]
	Physical Model	3.02	0.99	48.53	47.03	44.94	43.27	41.41	18.53	23.92	27.81	32.16	35.47
Experiment 1	CFD (Fluent) Model	3.02	0.99	48.53	47.402	46.04	44.372	42.285	18.53	24.841	29.73	33.614	36.74
	Error (%)	0.00%	0.00%	0.00%	0.79%	2.45%	2.55%	2.11%	0.00%	3.85%	6.90%	4.52%	3.58%
Experiment 2	Physical Model	2.96	1.91	43.8	41.94	39.56	37.56	35.52	18.59	22.09	24.88	28.02	30.4
	CFD (Fluent) Model	2.96	1.91	43.8	42.193	40.466	38.603	36.58	18.59	22.037	24.852	27.432	29.827
	Error (%)	0.00%	0.00%	0.00%	0.60%	2.29%	2.78%	2.98%	0.00%	0.24%	0.11%	2.10%	1.88%

Table 4-9: Results comparing physical model vs CFD results.

This data was then plotted to better visualise the data as shown in figure 4-21 and 4-22 below.



Figure 4-21: Chart showing physical vs CFD results – experiment 1 (1 lpm).



Figure 4-22: Chart showing physical vs CFD results - experiment 2 (2 lpm).

These results give an average error of 1.28% on the hot water system, but 12.02% on the cold-water system. Since the physical system contains less heat overall, it is hypothesized the main difference in these results is due to the assumption the acrylic walls are adiabatic and not suitable. The error was noted to be considerably less in the higher flow experiment, and it is hypothesized this is due to less time for heat losses with the higher flow than in the lower flow experiment.

4.3.3 Model Optimisation

To reduce the error between the CFD and physical model, the CFD boundary conditions were updated to include convection losses through the long sections of acrylic wall. In the Fluent module, the "insulated wall" selection boundary condition setup was changed from adiabatic to convection with heat transfer coefficient of

25 W/m².K, ambient temperature of 290K and shell conduction with settings of 0.002m thickness of acrylic material.

Due to the addition shell conduction, which adds elements, the mesh was changed to the setting found optimal in section 4.2.4. The calculations were completed again for both experiment 1 and 2 and compared to the physical models. The results converged with residuals slightly lower than the original models. The results were still not within acceptable error tolerance to verify the model.

During the physical experiment the test equipment was observed to be aged and the hot water circuit was discoloured, indicating surface rust and scale present within the system. The setup procedure of the Armfield instruction manual discussed flowing 80°C water through the system to remove any air bubbles. The experimental jig used could only achieve about 50°C. It is possible air bubbles remained trapped in the system.

The Fluent model was however modelling perfect conditions. This scale, corrosion and fouling would reduce the effectiveness of the heat exchanger as shown in section 2.3, so the thermal conductivity of the stainless steel was lowered to a final value 6 W/(m K). The thickness of the transfer wall was slightly increased and the convection transfer coefficient updated to 50W/m².K. With these changes the CFD model now appeared to better represent the physical experiment.

4.3.4 Results after Optimisation

The results after the optimisation from section 4.3.4 was tabulated to compare to the original physical models as shown in table 4-10 below. For better visualisation they were also plotted as seen in figure 4-23 and 4-24 below.

Comparisen of Physical and CFD modelling after optimisation		Hot Water Flowrate Fhot [l/min]	Cold Water Flowrate Fcold [l/min]	Temp T1 [°C]	Temp T2 [°C]	Temp T3 [°C]	Temp T4 [°C]	Temp T5 [°C]	Temp T6 [°C]	Temp T7 [°C]	Temp T8 [°C]	Temp T9 [°C]	Temp T10 [°C]
	Physical Model	3.02	0.99	48.53	47.03	44.94	43.27	41.41	18.53	23.92	27.81	32.16	35.47
Experiment 1	CFD (Fluent) Model	3.02	0.99	48.53	47.402	46.04	44.372	42.285	18.53	24.841	29.73	33.614	36.74
	Error (%)	0.00%	0.00%	0.00%	0.79%	2.45%	2.55%	2.11%	0.00%	3.85%	6.90%	4.52%	3.58%
Experiment 2	Physical Model	2.96	1.91	43.8	41.94	39.56	37.56	35.52	18.59	22.09	24.88	28.02	30.4
	CFD (Fluent) Model	2.96	1.91	43.8	42.193	40.466	38.603	36.58	18.59	22.037	24.852	27.432	29.827
	Error (%)	0.00%	0.00%	0.00%	0.60%	2.29%	2.78%	2.98%	0.00%	0.24%	0.11%	2.10%	1.88%

Table 4-10: Tabular results comparing physical model vs CFD results after optimisation.



Figure 4-23: Chart showing physical vs CFD results – experiment 1 (1 lpm).



Figure 4-24: Chart showing physical vs CFD results – experiment 2 (2 lpm).

These results give an average error of 2.07% on the hot water system, 2.90% on the cold-water system and 2.48% overall. This is considered acceptable, and the model was validated as these values fall within the accuracy of the equipment used within the Armfield HT36 experiments shown in section 4.3.1.

4.4 Phase 4: Global Temperature Distribution with Control Valve

To investigate the control valve impacts on the global temperature distribution throughout the heat exchanger, both physical and CFD experiments were compared and analysed.

4.4.1 Physical Model with Control Valve

Design of Experiment

The test equipment being modelled in the physical experiments with the control valve is the same as used to validate the computational model in section 4.1. Initially physical experimental data was gathered to analyse the effect of the control valve on the global temperature distribution through the heat exchanger.

The test equipment was set up in counter-flow arrangement using all four tubes. The equipment was turned on and the hot water allowed to heat and circulate to purge out any air bubbles. The cold-water side was also allowed to flow and clear out any air bubbles.

Once the setup was complete, the entry conditions were set to pre-determined flow rates and temperatures given in the manual. The flow rates and temperatures throughout the experimental rig were logged using the Armfield HT36 software. These logs were exported for data analysis and compared to the ANSYS model.

The flow rate for the cold water was set to maximum (built in control valve fully open). The butterfly valve at the entry region of the heat exchanger tubes, shown in figure 4-25, was then used to throttle the cold-water flow rate until it reached the test values shown in table 4-11 below.

Test Case	Parameter	Value				
	Hot Water In	30°C above cold water temperature				
1	Hot Water Flow	3 lpm				
-	Cold Water In	Temperature of the tap water				
	Cold Water Flow	1 lpm (manually throttled)				

 Table 4-11: Physical experiment boundary conditions with valve.



Figure 4-25: The manual control valve at the heat exchanger entry point.

Experimental HSE Risk

The experiment for phase 4 was completed on the same day as the experiment in section 4.1. All the same risks and controls were applicable and considered during this experiment. See appendix C for the full risk assessment.

Experiment Details

The experiment was performed in the University of Southern Queensland labs on the morning of 24th of May 2021. The ambient temperature was 17°C during the experiment. The experiments were undertaken and completed in accordance with the experiment design. There were no concerns.

Results

The results were recorded using the Armfield software and exported to excel. The tabulated values from the nine records can be seen in figure 4-12 below.

Sample Number	Elapsed Time [mm:ss]	Temp T1 [°C]	Temp T2 [°C]	Temp T3 [°C]	Temp T4 [°C]	Temp T5 [°C]	Temp T6 [°C]	Temp T7 [°C]	Temp T8 [°C]	Temp T9 [°C]	Temp T10 [°C]	Hot Water Pump Setting [%]	Hot Water Flowrate Fhot [l/min]	Cold Water Valve Setting [%]	Cold Water Flowrate Fcold [l/min]
1	00:00	48.5	46.8	44.7	43.0	41.0	18.5	23.8	27.8	32.0	35.2	46	2.9	100	0.94
2	00:05	48.5	46.8	44.8	43.1	41.2	18.5	23.9	27.7	31.9	35.2	46	3.0	100	0.95
3	00:10	48.7	47.0	44.8	43.1	41.1	18.5	23.8	28.0	32.0	35.2	46	3.0	100	1.06
4	00:15	48.7	47.1	45.0	43.1	41.2	18.5	23.9	27.7	32.0	35.4	46	3.0	100	0.93
5	00:20	48.5	47.1	45.1	43.3	41.3	18.5	24.2	27.4	32.0	35.4	47	3.1	100	0.95
6	00:26	48.7	47.1	45.0	43.2	41.2	18.5	24.0	27.6	32.2	35.2	46	3.0	100	0.95
7	00:31	48.5	47.1	45.0	43.2	41.2	18.5	24.0	27.6	32.0	35.4	46	3.1	100	0.93
8	00:36	48.7	47.1	45.0	43.2	41.2	18.5	23.8	27.8	32.0	35.4	46	3.0	100	1.04
9	00:41	48.8	47.1	45.0	43.3	41.2	18.5	24.1	27.8	32.1	35.3	46	3.1	100	1.05

Table 4-12: Results from physical experiment with the valve.

These results can be seen to look very similar to the results from physical experiment 1 using the system control valve rather than the manual valve near the entry condition. This was investigated in more depth in section 4.6.

4.4.2 CFD Model with Control Valve

Base Model

The base model used was identical to the model optimised during section 4.2, however a control valve was added to the cold-water entry region of the model as described below.

Control Valve angle

To make the comparison of the physical model to the CFD model, the butterfly valve angle needed to be as close as possible to the physical model. As there was no gauge on the valve, the image was loaded into an online protractor tool to measure the angle as shown in figure 4-26 below.



Figure 4-26: Online protractor tool to measure the valve angle. (https://www.ginifab.com/feeds/angle_measurement/ 2021). The angle was measured at 38° from fully open or 52° from fully closed.

Control Valve Modelling

The butterfly control valve was added as a simple circular disk and an angle of 38° from the open position. Butterfly valves come in many shapes and sizes with varying levels of complexity depending on their working environment. In the Armfield HT36 experimental jig, the valves are small and plastic so were assumed to be a very simple shape.

The valve was modelled as plane circular cross-sectional extrusion with 0.25mm radius on the edges. The outside diameter is 8.25mm to allow some clearance on the inside diameter of the cold-water fluid, as it was assumed when the valve was open, there would be water passing on all edges as it would be off the seal. The thickness has been selected as 1mm as most valves in industry have about 0.1-0.2 thickness relative to the diameter. The valve was inserted in the centre of the cold-water domain inlet 12mm from the centre of the main pipe.

This control valve body was then subtracted from the cold-water domain using a Boolean subtraction. To be able to add a finer mesh around the valve, the valve was also left in the model as a part. The new part was integrated into the main heat exchanger.



Figure 4-27: Control valve created in CFD model.

Mesh

With the mesh left at the optimised values from section 4.3 the mesh can be seen to in inadequate around the valve feature.



Figure 4-28: Cross section of the mesh around the valve feature showing inadequate mesh.

The mesh was refined by creating a 0.15mm face elements mesh feature for the faces of the cold-water domain which contacted the valve body and also on the edge of the cold-water domain in the entry region. After this refinement, the model had a total of 230,000 elemensts, leaving room for more refinement when we study this region is more detail in section 4.5.



Figure 4-29: Cross section of the mesh around the valve feature showing refined mesh.

Fluent Setup

The fluent setups were the same as the models from section 4.2 and 4.3 with some additional settings to the body and transfer wall where the valve has been added to the model. All the material properties from section 4.2.2 were replaced with the optimised values from section 4.3.4 to match the inefficient heat exchanger equipment.

Material	Density	Specific Heat Thermal		Viscosity	Heat Transfer	
	(kg/m^3)	(J/(kg K)	Conductivity	(kg/(m s)	Coefficient	
			(W/(m K)		(W/m^2.K)	
Water @ 20°C	998.2	4182	0.6	0.001003	N/A	
Stainless Steel	7900	477	5	N/A	N/A	
Insulation (acrylic)	1410	1395	1.5	N/A	N/A	
Still Air	N/A	N/A	N/A	N/A	50	

Table 4-13: ANSYS initial valve model material properties.

The boundary conditions were matched to the physical experiment averaged readings from section 4.4.1 and can be seen in table 4-14 below.

Test Case	Parameter	Value
	Hot Water In	48.6°C = 321.6K
	Hot Water Flow	3.00 lpm
	Hot Water Mass Flow (calculated)	0.04991kg/s
1	Cold Water In	18.50°C = 291.50 K
	Cold Water Out	0.98 lpm
	Cold Water Mass Flow (calculated)	0.01630 kg/s
	Ambient Temperature	$17^{\circ}C = 290 \text{ K}$

Table 4-14: ANSYS initial valve model boundary conditions.

The Fluent parameters were setup with similar values/settings as the experiments from section 4.2.

Area	Parameter	Comments
Setup – Models	Energy Equation	Turned on.
Setup – Models	Viscous Model	k-epsilon Realizable Enhanced Wall Treatment
Setup – Materials	Fluids	Water-liquid setup
Setup – Materials	Solids	Steel-stainless setup Acrylic setup
Setup - Cell Zone Conditions	Cold water domain Hot water domain	Setup as fluid – water-liquid
Setup - Boundary Conditions	T5 – Hot water out T10 – Cold water out	Setup as mass flow outlet with flow rate matched to the inlet. Pressure outlet was tested with same results
Setup - Boundary Conditions	T1 – Hot water in T6 – cold water in	Setup as mass flow inlet Setup flow rate as normal to boundary with flow rate and temperature as per actual results in 4.4.1
Setup - Boundary Conditions	Insulated Wall – Cold water domain Insulated Wall – Hot water domain	Setup convection heat transfer with acrylic material value and single layer shell conduction of thickness

Table 4-15: ANSYS initial valve model fluent parameter setup.

		0.001m, ambient temperature of
		290К
		Setup convection heat transfer with
Satup Boundary		stainless steel material value and
Conditions	Convection wall	single layer shell conduction of
Conditions		thickness 0.0006m, ambient
		temperature of 290K
		Setup as coupled transfer with the
Satup Boundary		shadow equivalent. Setup as single
Conditions	Transfer wall	layer steel-stainless shell
Conditions		conduction with wall thickness of
		0.0013m
Setup - Boundary	Cold water domain to valve wall	Acrylic with no heat transfer
Conditions		The fire with no near transfer
Solution – Method	Scheme	Coupled
Solution – Monitors	Residuals	All changed to 1E-06
Solution – Initialization	Method	Hybrid Initialization
Run Calculation	Number of Iterations	1000

Results

The temperature distribution values were extracted from ANSYS Results model. The temperatures at each location were calculated using a function of Mass Flow Average across a cross-sectional cut as can be seen in table 4-16 below.

Test Case	Parameter	Result
1	T1 (Hot In)	321.60 K
	T2 (Hot – bend 1)	320.46K
	T3 (Hot – bend 2)	319.06 K
	T4 (Hot – bend 3)	317.35 K
	T5 (Hot Out)	315.18 K
	T6 (Cold In)	291.50 K
	T7 (Cold – bend 3)	298.01 K
	T8 (Cold – bend 2)	303.05 K
	T9 (Cold – bend 1)	307.02 K
	T10 (Cold Out)	310.22 K

 Table 4-16: Temperature distribution reported at fixed locations throughout the heat exchanger.
To verify the valve was correctly modelled, the velocity profile was inspected around the valve using a velocity contour on a cut through the X-Y plane of the model. This showed results as expected with higher velocities around the edge of the valve and near-still stops near the centre of the valve and on the pipe edges. The results was noted to have some pixelisation and visible contours likely due to the course mesh.



Figure 4-30: Velocity contour around throttling valve to verify modelling.

To discuss whether the valve has had any influence of the global temperature distribution throughout the heat exchanger, the results of both the physical experiments and the CFD models has been analysed.

Physical to CFD Model error

The physical results were tabulated as seen in table 4-17 below. To help visualise the results, the results of each set of experiments were plotted and can be seen in figures 4-31 and 4-32 below.

Comparison o models with	f Physical and CFD and without valve	Hot Water Flowrate Fhot [l/min]	Cold Water Flowrate Fcold [l/min]	Temp T1 [°C]	Temp T2 [°C]	Temp T3 [°C]	Temp T4 [°C]	Temp T5 [°C]	Temp T6 [°C]	Temp T7 [°C]	Temp T8 [°C]	Temp T9 [°C]	Temp T10 [°C]
Without Valve (From 4.1 & 4.3)	Physical Model CFD (Fluent) Model Error (%)	3.02 3.02 0.00%	0.99 0.99 0.00%	48.53 48.53 0.00%	47.03 47.402 0.79%	44.94 46.04 2.45%	43.27 44.372 2.55%	41.41 42.285 2.11%	18.53 18.53 0.00%	23.92 24.841 3.85%	27.81 29.73 6.90%	32.16 33.614 4.52%	35.47 36.74 3.58%
With Valve (From 4.4.1 & 4.4.2	Physical Model CFD (Fluent) Model Error (%)	3.00 3.00 0.00%	0.98 0.98 0.00%	48.6 48.6 0.00%	47.0 47.46 0.98%	44.9 46.6 3.79%	43.1 44.35 2.90%	41.2 42.18 2.38%	18.6 18.6 0.00%	23.9 25.01 4.64%	27.7 30.05 8.48%	32.0 34.02 6.31%	35.3 37.22 5.44%

 Table 4-17: Results of the physical and CFD experiment at 11pm with and without the valve.



Figure 4-31: Plot of the results of the physical and CFD experiment at 11pm without the valve.



Figure 4-32: Plot of the results of the physical and CFD experiment at 11pm with the valve.

The error between the physical and CFD models for the case without the valve was discussed in section 4.3. It was found the models matched within 3.34%. In the case with the valves, it was found that the physical and CFD models matched with an error of 4.37%. Both are accurate enough for this study and fall within the accuracy reliability of the thermocouples used within the physical experiment.

Models With and Without Valve

To understand if the valve had influenced the overall temperature distribution throughout the heat exchanger, the physical and CFD models, both with and without the valve, were analysed to see if there were notable differences.

The data was tabulated in a way to allow comparison of the four datasets and display the errors as shown in table 4-18. The physical experiments with and without the valve were compared to each other and this was duplicated for the CFD experiments.

Comparisen o with	f Physical and CFD models and without valve	Hot Water Flowrate Fhot [l/min]	Cold Water Flowrate Fcold [I/min]	Temp T1 [°C]	Temp T2 [°C]	Temp T3 [°C]	Temp T4 [°C]	Temp T5 [°C]	Temp T6 [°C]	Temp T7 [°C]	Temp T8 [°C]	Temp T9 [°C]	Temp T10 [°C]
	Without Valve	3.02	0.99	48.53	47.03	44.94	43.27	41.41	18.53	23.92	27.81	32.16	35.47
Physical Model	With Valve	3	0.98	48.6	47	44.9	43.1	41.2	18.6	23.9	27.7	32	35.3
	Error (%)	0.66%	1.01%	0.14%	0.06%	0.09%	0.39%	0.51%	0.38%	0.08%	0.40%	0.50%	0.48%
	Average Error (entry conditions)	0.55%											
	Average Error (Dependants)	0.31%											
	Without Valve	3.02	0.99	48.53	47.4	46.04	44.372	42.285	18.53	24.841	29.73	33.6	36.74
CFD Model	With Valve	3.00	0.98	48.6	47	44.9	43.1	41.2	18.6	23.9	27.7	32	35.3
	Error (%)	0.66%	1.01%	0.14%	0.85%	2.48%	2.87%	2.57%	0.38%	3.79%	6.83%	4.80%	3.92%
	Average Error (entry conditions)						0.55%						
	Average Error (Dependants)						3.51%						

Table 4-18: Data comparing the differences between experiments with and without the valve.

The physical model revealed the average differences between the temperature at the fixed measurements points was 0.31% and a difference of 0.55% in the entry temperatures and flow rates. In the CFD model it the average differences between the temperature at the fixed measurements points was 3.51% also and a difference of 0.55% in the entry temperatures and flow rates. It is hypothesised the higher percentage error in the CFD model is due to differences in meshing. The model was then optimised specifically for the valveless model rather than an actual effect of the valve in the entry region. This CFD model had slightly higher error compared to the physical model in the previous section.

This data can be visualised in the plots in figure 4-33 and 4-34.



Figure 4-33: Plot of the physical experimental results with and without the valve.



Figure 4-34: Plot of the CFD experimental results with and without the valve.

Findings

The percentages in temperature differences errors indicate that there is no effect to the global temperature distribution from the control valve in the entry region of the heat exchanger.

4.5 Phase 5: Analyse Cold Water Entry Region

In section 4.4 several physical and computational experiments were performed to investigate the effects of the control valve in the entry region of the heat exchanger. In section 4.5 these experiments were further refined with specific analysis around the entry region with and without a valve. Unlike the global level, these cannot be physically measured, so in this section only computational analysis is available. To get better mesh resolution in the areas around the valve and reduce unnecessary calculations in the remainder of the exchanger, a detailed local entry region model was created for the analysis.

4.5.1 Design of Experiment

This part of the study determines if the control valve will influence the local heat distribution within the entry region of the heat exchanger. To do this, a 4-stage process was used:

- Create a verified model
- Compare and choose turbulence model
- Completed a mesh independence study to determine suitable mesh to reduce processing time for multiple calculations
- Complete analysis for various valve open positions and compare to model without valve.

The control valve will be modelled at various openings. This is because, in industrial applications, the size of the pump could vary which would result in different valve open positions. The study will be done on the same boundary conditions as the physical experiment from section 4.1 with 11pm cold-water flow.

4.5.2 Verification Model Creation

The shape and sizing of the model was kept the same as the global exchanger modelling from section 4, however the model was reduced to a limited section containing the cold-water inlet, hot water outlet and 125mm of the main tube. 125mm was chosen to give adequate length for the turbulence effects of the valve to normalise as shown in the literature review (Song, Wang, Park 2009), (Janusz and Czeslaw 2016). The entrance region for internal turbulent flow is generally assumed to be 10x the tube diameter before the flow is considered fully developed (Cengel & Ghajar 2015), so after this region no further affects from the valve are expected.

Assumptions

All the material properties will be returned to the ideal values as the global inefficiencies are no longer required for analysis of the local effects of the valve. All external walls will now be considered fully insulated as the global heat losses through these sections are not required for analysis of the local effects of the valve.

3D Model



Figure 4-35: ANSYS model of entry region of the heat exchanger.

The heat exchanger entry region model is made of three parts:

- Hot water domain: Diameter of 8.325mm, 25mm length protruding past the start of the cold-water domain, 125mm long when aligned with the cold-water domain
- Cold water domain: Diameter of 12mm of the main 125mm length section, diameter of 8.325 feed in section with 5mm offset from the end of the tube
- Valve: 1mm width with 0.25mm chamfers, diameter of 8.25mm to give some clearance on OD to assume not sitting on seal, offset 12.5mm from the main tube centreline with an initial angle of 52°.

These parts were combined in DesignModeler to make a single part with three components.

Mesh

A mesh was created to get good resolution through the cold-water domain and the transfer wall between the cold and hot water domains. The mesh was optimised to get the maximum number of elements without going over the allowable limit of 512,000 for ANSYS student edition, understanding that also some elements will be generated when using the shell conduction method.

Hot water Domain:

- Method: Sweep mesh, using hot water entry face as source and outlet as the target
- Mesh Type: All Quad
- Divisions: 60
- Edge Divisions: 52
- **Bias:** No Bias.

Hot water Domain:

- **Method:** Tetrahedrons
- **Body Sizing:** 0.0007m
- **Face Sizing:** Around the valve 0.0002m.

Resulting Mesh: 465,279 elements.



Figure 4-36: External mesh in ANSYS model of entry region of the heat exchanger.



Figure 4-37: Sectioned mesh of ANSYS model showing detail around valve.

Defining Region Names

The key features of the 3D model were named for correct allocation of boundary conditions in the ANSYS module.



Figure 4-38: Named sections: hot and cold inlets and outlets.



Figure 4-39: Named sections: transfer wall, valve and hot water domain.



Figure 4-40: Named sections: cold water domain and insulated wall.

Validation Data from Previous Models

To get the hot water in temperatures at 125mm from the tube ends, the results from the section 4.3 were analysed.

Table 4-19:	Entry	region	model	material	properties.
-------------	-------	--------	-------	----------	-------------

Cold Water Flow Rate	Hot Water IN @ 125mm	Cold Water OUT @ 125mm	Hot water OUT
1 lpm	315.9 K	293.5	315.29 K
2 lpm	310.1 K	292.9	309.58 K

Material Properties and Boundary Conditions

Table 4-20: Entry region model material properties.

Material	Density	Specific	Thermal	Viscosity	Heat	Source
	(kg/m^3)	Heat	Conductivity	(kg/(m s)	Transfer	
		(J/(kg	(W/(m K)		Coefficient	
		K)			(W/m^2.K)	
Water @	998.2	4182	0.6	0.001003	N/A	ANSYS Library
20°C						
Stainless	7900	477	14.9	N/A	N/A	(Cengel & Ghajar
Steel						2015)
Insulation	1410	1395	0.2	N/A	N/A	(Dielectric
(acrylic)						Manufacturing 2020) /
						(Energy Education 2020)

Table 4-21: Entry region model boundary c	conditions.
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Parameter	Value
Hot Water In @ 125mm from origin	315.9 K
Hot Water Flow	3.00 lpm
Hot Water Mass Flow (calculated)	0.04991kg/s
Cold Water In	291.50 K
Cold Water Out	0.98 lpm
Cold Water Mass Flow (calculated)	0.01630 kg/s

Table 4-22: ANSYS entry region model Fluent parameter setup.

Area	Parameter	Comments
Setup – Models	Energy Equation	Turned on
Satup Models	Viscous Model	k-epsilon; Realizable
Setup – Models	viscous model	Enhanced Wall Treatment
Setup – Materials	Fluids	Water-liquid setup
Setup - Materials	Solids	Steel-stainless setup
Setup – Materials	50105	Acrylic setup
Setup - Cell Zone	Cold water domain	Setup as fluid – water-liquid
Conditions	Hot water domain	Setup as nuid – water-inquid
Setup - Boundary	T5 – Hot water out	Setup as mass flow outlet with flow
Conditions	Cold water out	rate matched to the inlet.
		Setup as mass flow inlet
Setup - Boundary	Hot water in	Setup flow rate as normal to
Conditions	T6 – cold water in	boundary with flow rate and
		temperature as per table 4-21
Setup - Boundary	Insulated Wall – Cold water domain	Satur as not heat transfer
Conditions	Insulated Wall – Hot water domain	Setup as not near transfer
		Setup as coupled transfer with the
Setup - Boundary	Transfer wall	shadow equivalent. Setup as single
Conditions		layer steel-stainless shell conduction
		with wall thickness of 0.0006m
Setup - Boundary	Cold water domain to valve wall	Acrylic with no heat transfer
Conditions		
Solution – Method	Scheme	Coupled
Solution – Monitors	Residuals	All changed to 1E-06
Solution – Initialization	Method	Hybrid Initialization
Run Calculation	Number of Iterations	500

Convergence of Calculations

After 500 iterations, the approximate average residual values were obtained:

- X, Y Velocities: 6e-7
- Z velocity: 8e-7
- Continuity equation: 4E-4
- Energy equation: 1.4E-7
- Epsilon: 4e-5
- k: 4e-6.



Figure 4-41: Residuals of entry region validation case

Results

To validate the new entry region model, a few parameters and plots were checked. Firstly, the temperature outlets of the hot and cold temperature were validated against the values from the CFD model in section 4.2.

Table 4-23:	Temperature	validation	of entry	region	CFD model.
-------------	-------------	------------	----------	--------	------------

	Data from 4.2	Entry Region Model	Error
Hot Water OUT	315.3 K	315.2 K	0.1 K (0.03%)
Cold Water OUT @ 125mm	293.5 K	293.8 K	0.3 K (0.10%)

Charts were created to validate that the temperature contour across the entry region section of the exchanger is correctly transferring heat from the hot to cold domains.



Figure 4-42: Temperature contour showing correct transfer of heat.

A velocity contour in the cold-water domain was created around the valve to ensure the models was correctly showing high velocity where the fluid needed to pass around the valve.



Figure 4-43: Velocity contour showing expected velocity profile around valve.

The mass flow rates at the entry and exits of each domain were checked to ensure segregation of the two fluids and ensure there was no gain or loss of mass.

(kg/s)	Mass Flow Rate
-0.0163 0.04991 -0.04991 0.0163	cold_outlet hot_inlet t5_hot_outlet t6_cold_inlet
-5.2041704e-17	Net

Figure 4-44: Image showing correct balance of mass flow.

From this analysis, the model was considered to be verified as a working model.

4.5.3 Compare Turbulence Model

As discussed in the literature review, there are various turbulent models within CFD software to model different fluent flows and interactions. Some models are better for modelling fluid flow over an object whilst others better for modelling fluid flow through a pipe. This study includes both flow around the valve object and flow through enclosed pipe, so an easy selection of the correct model cannot be made. Research showed that no single model is better for modelling around a butterfly valve but that each method should be tried and analysed to get the best results (Sung-Woong et al. 2021).

The models that will be considered are the three mainstream models:

- k-ε Model Options: Realisable and Enhanced Wall Treatment
- k-ω Model Default Fluent settings
- k-ω Model SST

To see which model produces the results we would expect, the results were inspected for various phenomenon through several result reports:

- 2D streamline of the cold water around the valve
- 3D streamlines of the cold water
- 2D velocity contour
- 2D temperature distribution
- Residuals in the Fluent calculations.

2D Streamline

A cut was made on the X-Z plane in the cold-water domain. A surface streamline was created with 300 points.



Figure 4-45: 2D streamline on X-Z plane using k-c turbulence model.



Figure 4-46: 2D streamline on X-Z plane using k- ω turbulence model.



Figure 4-47: 2D streamline on X-Z plane using SST turbulence model.

All three models showed very similar results with streamlines around the valve representing expected profile. There were slight differences in the velocity profile after the sharp corner to the top of the main tube image. There were also differences in the velocity profile in the bottom corner of the main tube.

3D Streamlines

A 3D streamline was created with 300 points.



Figure 4-48: 3D streamline using k-ɛ turbulence model.



Figure 4-49: 3D streamline using k- ω turbulence model.



Figure 4-50: 3D streamline using SST turbulence model.

The 3D streamlines showed a much calmer velocity profile in the top of the main tube after the sharp corner with the k- ϵ model. The two k- ω models were similar with the standard model showing more turbulence.

2D Velocity Contour

A cut was made on the X-Z plane in the cold-water domain and a surface velocity contour was created with 100 contours.



Figure 4-51: 2D velocity contour on X-Z plane using k-ɛ turbulence model.



Figure 4-52: 2D velocity contour on X-Z plane using k- ω turbulence model.



Figure 4-53: 2D velocity contour on X-Z plane using SST turbulence model.

There was no significant visually difference in the velocity contours between turbulence models.

2D Temperature Distribution

A cut was made on the X-Z plane in the cold-water domain and a temperature contour was created with 100 contours.



Figure 4-54: 2D temperature contour on X-Z plane using k-c turbulence model.



Figure 4-55: 2D temperature contour on X-Z plane using k- ω turbulence model.



Figure 4-56: 2D temperature contour on X-Z plane using SST turbulence model.

There was no significant visual difference in the temperature contours between turbulence models.

Fluent Residuals

Each set of calculations used identical geometry, mesh, material properties, setup, and boundary conditions with the only deviation being the turbulence model used. To compare the validity of the results, the Fluent scaled residuals were compared to ensure the results converged.

	k-ε Model	k-ω-Standard	k- ω - SST
Continuity	4.5E-4	2.6E-3	1.6E-2
X-velocity	5.0E-7	3.1E-6	1.8E-5
Y-velocity	5.0E-7	2.0E-6	1.0E-5
Z-velocity	7.0E-7	2.2E-6	1.0E-5
Energy	1.0E-8	1.2E-7	6.3E-7
К	4.5E-6	8.0E-6	5.0E-5
Omega/Epsilon	4.0E-5	2.1E-5	1.0E-4
Comments	Best – Considered	Considered Converged	1 order of magnitude less
	Converged		

Table 4-24: Summary of approximate scaled residuals for the different turbulence models.

All three methods produced similar results that would appropriate for this study, however the velocity streamlines from the \mathbf{k} - $\boldsymbol{\omega}$ models seemed to be the most realistic following the sharp corner. With the SST model not converging appropriately, the standard \mathbf{k} - $\boldsymbol{\omega}$ model was chosen as the turbulence model for section 5 of this study.

4.5.4 Mesh Independence Study

A mesh independence study was performed to ensure the results being obtained were stable and correct. Since many computations were to be performed a mesh independence study was completed to find a mesh size suitable for getting accurate calculates whilst minimizing computation time to complete the study. To complete this study, 14 fluent studies were run with various mesh sizing and the results tabulated. The model from 4.5.2 was used with the **k**- ω turbulence model from section 4.5.3 for the independence study.

Three resulting categories were reviewed and compared.

- Convergence Error Representation: Each study was compared to the baseline for the X,Y&Z velocity, continuity equation and energy equation residuals. To compare to the baseline, any value larger than the baseline was averaged and compared to the baseline in percentage error
- Wall Pressure: The wall pressure of the hot and cold domains 30mm from the start of the main tube was compared to the baseline as a percentage error
- Mass Flow Rate: The mass flow rate of the hot and cold domains 30mm from the start of the main tube was compared to the baseline as a percentage error
- Element Reduction: Each study was compared to the based for the total elements generated through the mesh setup. The mesh was compared to the baseline using a percentage

• A subject visual inspection of the streamlines around the valve and following the sharp corner was also performed to ensure no unusual results were being missed at lower mesh element counts.

The full results of the mesh independence study can be found in Appendix E. The resulting elements were plotted against the dependant variables to determine if the study was mesh dependant. Analysis of the results in figure 4-57 below shows that the results are mesh dependant and stability is achieved with a mesh count of approximately 375,000 elements.



Figure 4-57: Mesh independence study results showing stability after approximately 375,000 elements.

Since this is not significantly reducing the elements amount and accuracy is important for this study, the mesh was left at the max element settings.

Hot water Domain:

- Method: Sweep mesh, using hot water entry face as source and outlet as the target
- Mesh Type: All Quad
- Divisions: 60
- Edge Divisions: 52
- Bias: No Bias.

Hot water Domain:

- Method: Tetrahedrons
- **Body Sizing:** 0.0007m
- Face Sizing: Around the valve 0.0002m.

Resulting Mesh: 465,279 elements.

4.5.5 Comparative model without Valve

To investigate if any local hot spots are due to the valve or not, a control model was created without the valve in the entry region. This control model was the same with the only adjustment being the removal of the valve feature. The mesh was re-generated without the face sizing as the valve no longer exists in this model, resulting in 426,856 elements.

The Fluent software was setup with the same boundary conditions, material properties and configurations as the model with the valve including the use of the \mathbf{k} - $\boldsymbol{\omega}$ standard turbulence model. The calculation was run with 500 iterations. The results without the valve are in the figures below.



Figure 4-58: Residuals for the entry region model without valve.



Figure 4-59: 2D velocity streamlines for the entry region model without valve.



Figure 4-60: 3D velocity streamlines for the entry region model without valve.



Figure 4-61: 2D velocity contour for the entry region model without valve.



Figure 4-62: 2D temperature contour for the entry region model without valve.

4.5.6 Analysis

Cross-section cuts were made through the CFD models, and the lowest, highest, and average temperatures analysed between the two scenarios. As the heat distribution is likely to be most affected closest to the valve, cuts were made every 1mm for the first 12mm, 2mm for the next 12mm and 5mm up to 49mm from the cold-water domain start wall. As the fouling is most likely to occur in the hot water side, the measurements were taken by creating the cut with a radius of 4.5mm in the cold-water domain, resulting in a sample of <1mm from the transfer wall as shown in figure 4-63 below.



Figure 4-63: Example of sample cut to measure min, max and average temperature close to transfer wall.

Data was collected from multiple experiments at various valve open positions to investigate if valve position influences the heat distribution. The angles chosen were 15° , 30° , 45° and 60° from the valve being fully open. Note: 75 degrees was attempted, however the gap around the valve was too small causing flow to stop and the calculations did not converge.

To get the values, the function calculator in the ANSYS results module was used at each cut location for each of the models. For maximum temperature the "maxVal" function was used, for minimum temperature the "minVal" function was used, and for average temperatures the "massFlowAve" function was used.

Results

The ANSYS experiments were completed and the data tubulised which can be seen in full in appendix F. To analyse the data the temperature results were compared across the various valve positions. Figure 4-64 shows the minimum temperatures in the wall region for each model. This data shows very little variation in minimum temperature with less than 1 degree difference at any location along the test length. Figure 4-65 shows the maximum temperatures in the wall region for each model. This data shows significant variation between the baseline data and the data from the valves with the highest angle from fully open. This data is discussed in more detail later in this section. Figure 4-66 shows the average temperature in the wall region for each model. This data shows very little variation for each model. This data shows very little variation for each model and the data is discussed in more detail later in this section. Figure 4-66 shows the average temperature in the wall region for each model. This data shows very little variation in the average temperatures between each model. Two outliners can be seen and are being considered irrelevant to the study due to this location being right near the sharp corner and an understanding that the average temperature would not really fluctuate to that degree.



Figure 4-64: Minimum temperature at the transfer wall region at various valve positions.



Figure 4-65: Maximum temperature at the transfer wall region at various valve positions.



Figure 4-66: Average temperature at the transfer wall region at various valve positions.

Figure 4-65 shows that the maximum temperatures of the different valve position trendlines seem to fluctuate significantly in the first 15mm of tube crossing each other and not showing any notable trend. This is shown in more detail in figure 4-67 below. Each valve positions temperature trend then takes an independent path between 15mm and 30mm from the start of the tube with significant variation between valve position trends. This is shown in more detail in figure 4-68 below.



Figure 4-67: Maximum temperature at the transfer wall region at various valve positions refined to 0-16mm.



Figure 4-68: Maximum temperature at the transfer wall region at various valve positions refined to 15-31mm.

In the region between 15 and 25mm from the cold-domain tube starting wall, it can be seen the two experiments with valves closed at 45° and 60° are showing maximum temperatures consistently above the baseline. With the 60° valve angle the temperatures can be seen to differ 3-4 degrees consistently through several data points. The two other experiments with valves at 15° and 30° have values which fluctuate below and above the baseline, however they both follow its' general trend.

Findings

This section analysied the entry region of the heat exchanger comparing CFD models with and without a valve. The data is showing when the valve angle is closed, to significantly change the flow rate of the fluid, there is higher maximum temperatures between 15-25mm in the tube's transfer wall region.

The author does not feel confident making a statement on the hypothesis at this stage until more experimental data is reviewed.

It is important to also note the limitations of these findings. As the valve got a higher angle the CFD calculations converged less, therefore indicating more error in the results. This was likely due to the high turbulence and erratic velocities.

5.0 Chapter 5: Scale and Optimisation

5.1 Introduction

Chapter 4 describes experiments that were performed and noted the resulting initial findings regarding the temperature distribution effects of a control valve in the entry region of a heat exchanger. These experiments were performed on a small-scale educational heat exchanger model with low temperature differentials. Real-life sized industrial applications of a heat exchanger are likely to be exposed to more extreme conditions and fluids which could change the outcome of the experiments.

In this chapter of the dissertation, the CFD models have been scaled up to better represent a real-life application of a heat exchanger. As noted in section 3.2.2, in an industrial real-life application it is unlikely a dual-tube style exchanger would be used but is none the less being used for this study.

5.2 Design of Experiment

Six experiments were performed on upsized models to verify if greater flow rates, large diameters and larger temperature differences reveal similar results to the small controlled experiments from chapter 4. The experiments performed were:

- Complete heat exchanger model with no valve in entry region
- Complete heat exchanger model with valve at real-life position
- Complete heat exchanger model with valve at near-closed position
- Entry-region heat exchanger model with no valve in entry region
- Entry-region heat exchanger model with valve at real-life position
- Entry-region heat exchanger model with valve at near-closed position.

Experiments 1 to 3 will be conducted to determine if the control valve influences the global temperature distribution throughout the heat exchanger core. Experiments 4 to 6 will determine if the control valve influences the local temperature distribution in the entry region transfer wall of the heat exchanger.

5.3 Data for Model

To scale this study to the application of a large engine test dynamometer, data was required on the heat generated in the application. Data for a high horse power (HHP) industrial engine was found on the internet (Cummins Inc 2016) and will be used as a broad example of real-life engine heat output. Note: these large engines often have two coolant circuits – main jacket water and low temperature circuits. Only the main water jacket data is to be used as it outputs significantly more heat:

- Engine Model: QSK78-G12
- **Power Output:** 2737kW
- Heat Rejection to Coolant: 48.3 MJ/min (805 kW)
- Max Flow Rate: 2222 L/min (0.037 $\frac{m^3}{s}$)

• Max Outlet Temp: 104°C.

To calculate the heat in the exchanger system, some assumptions on the heat exchanger needed to be made. A suitable industrial product available on the market was chosen. The product chosen is the PowerTest JW4500 suitable for engines producing up to 3356kW of power. Some key specifications (PowerTest 2015):

- Inlet/Outlet Diameter: 152mm
- Flow Rate: 1174 L/min $(0.020 \frac{m^3}{c})$
- Max Heat Rejection: 89075 BTU/min (1566 kW)
- Max Coolant Inlet Temp: 110°C
- **Coolant Outlet Temp:** 71-96°C
- Process (cold) Fluid: Water
- Cooling (Hot) Fluid: 50/50 Glycol/Water Mixture.

An industrial-type cooling tower which uses ambient air to cool was assumed to control the temperature of the cooling/process water. It was also assumed the water inlet temperature was 45°C. This is higher than the heat exchanger manufacturer's recommended inlet temperature, however, is more realistic in the application's environment. Process water will be assumed to be clean pure water. The system was assumed to be perfectly insulated with no losses and the heat exchanger will cool all the heat that has been rejected to the coolant.

The purpose of the heat exchanger in this application is to maintain the temperature outlet of the heat exchanger hot circuit to be 85°C, simulating a radiator. This allows the dynamometer test operators to identify when the test engine is producing too much heat during operation.

To calculate the required information, some material properties are required and were sourced as shown in table 5-1.

Material	Density (kg/m^3)	Specific Heat (J/(kg K)	Source
Water @ 45°C	990.1	4180	Cengel & Ghajar 2015
50/50 Glycol/Water	1030	3718	Engineering ToolBox
mixture @ 100°C			2013

Table 5-1: Material properties of heat exchanger fluids.

5.4 Calculations

To create scaled models in CFD software, four additional pieces of information were required:

- Dimensions of the heat exchanger for optimal cooling
- Hot water inlet temperature at operating conditions
- Cold water flow rate at operating conditions
- Angle of the control valve at operating conditions.

Heat Exchanger Dimensions

A simple system diagram was created as seen in figure 5-1 from the data in section 5.2 for the heat exchanger with parameters for the maximum cooling capacity. The hot water outlet temperature was assumed to be 85° C as this is approximately the middle of the specified range of the example equipment. The cold-water inlet is assumed to be 30° C which is the inlet temperature the equipment is rated at.



Figure 5-1: System diagram of scaled model for maximum cooling capacity.

To find the cold-water outlet temperature (Cengel & Ghajar 2015 [formula 11-9]):

$$\dot{Q} = \dot{m_c} c_{p,c} (T_{cold,out} - T_{cold,in})$$

To find m_c ;

$$\dot{m}_c = \dot{V}_c * \rho_c$$
$$\dot{m}_c = 0.020 \frac{m^3}{s} * 990.1 \frac{kg}{m^3}$$
$$\dot{m}_c = 19.80 \frac{kg}{s}$$

Substituting m_c back in:

$$\dot{Q} = \dot{m}_c c_{p,c} (T_{cold,out} - T_{cold,in})$$

$$1566 \ kW = 19.80 \frac{kg}{s} * 4180 \frac{J}{kg * K} (T_{cold,out} - 318K)$$

$$1566000 \frac{J}{s} = 19.80 \frac{kg}{s} * 4180 \frac{J}{kg * K} * (T_{cold,out} - 318K)$$

$$18.92 = T_{cold,out} - 318K$$

$$T_{cold.out} = 336.92K \approx 337K$$

To find the length of the heat exchanger (Cengel & Ghajar 2015 [formula 11-10]) was used in conjunction with the log mean temperature method.

$$\dot{Q} = U * A_s * \Delta T_m$$

A few assumptions had to be made:

- From the available data the overall heat transfer coefficient (U) could not be accurately calculated from forced convection formula. Instead, a U valve of $1700 \frac{W}{m^2.K}$ was chosen from a combination of reviewing standard tables (Cengel & Ghajar 2015 [Table 11-1]) (Engineering Toolbox 2003).
- The inner tube to annulus outside diameter ratio was kept the same as the original heat exchanger model with the annulus outside diameter considered to be the 152mm inlet sizing from the supplier information

To find the annulus inside diameter:

$$\frac{8.925}{14} = \frac{D_a}{152}$$
$$D_a = 96.9mm \approx 97mm$$

To find the log mean temperature difference of the exchanger (Cengel & Ghajar 2015 [formula 11-25]):

$$\Delta T_{lm} = \frac{\Delta T_1 - \Delta T_2}{\ln\left(\frac{\Delta T_1}{\Delta T_2}\right)}$$

For counter-flow exchangers, delta T values are found from:

$$\Delta T_1 = T_{hot.in} - T_{cold,out}$$
$$\Delta T_1 = 383K - 337K$$
$$\Delta T_1 = 46K$$

And:

$$\Delta T_2 = T_{hot.out} - T_{cold,in}$$
$$\Delta T_2 = 358K - 318K$$
$$\Delta T_2 = 40K$$

Substituting back in:

$$\Delta T_{lm} = \frac{46 - 40}{\ln\left(\frac{46}{40}\right)}$$

$$\Delta T_{lm} = 42.93 \, K$$

Substituting back in:

$$\dot{Q} = U * A_s * \Delta T_m$$

1566000W = 1700 $\frac{W}{m^2 \cdot K} * A_s * 43.93 K$
 $A_s = 20.97 \text{ m}^2$

To find the length:

$$A_{s} = \pi D L$$
$$L = \frac{A_{s}}{\pi * D}$$
$$L = \frac{20.97 m^{2}}{\pi * 0.097 m}$$
$$L = 68.81m \approx 69m$$

Whilst this length looks abnormally long, it is important to note the context of the size of the equipment and the heat being rejected into the system. This length is one of the reasons the industrial equipment in applications like this do not use a dual-tube type heat exchanger. Much more efficient plate-style heat exchangers are used. Plate style heat exchangers get much more surface area into a compact space. As an example, the PowerTest JW4500 plate-type heat exchanger these boundary conditions are based off, fits into a 4 m^3 space.

Hot Water Inlet Temperature

To calculate the hot water inlet temperature, a simple system diagram was created from the data in section 5.2 for the heat exchanger with parameters modified to represent actual figures for the engine model rather that the maximum capacity. This can be seen in figure 5-2 below.



Figure 5-2: System diagram of scaled model at operating conditions.

To find the hot water inlet temperature (Cengel & Ghajar 2015 [formula 11-10]):

$$\dot{Q} = \dot{m_h} c_{ph} (T_{hot,in} - T_{hot,out})$$

To find m_h ;

$$\dot{m}_h = \dot{V}_h * \rho_h$$
$$\dot{m}_h = 0.037 \frac{m^3}{s} * 1030 \frac{kg}{m^3}$$
$$\dot{m}_h = 38.11 \frac{kg}{s}$$

Substituting m_h back in:

$$\dot{Q} = \dot{m}_h c_{ph} (T_{hot,in} - T_{hot,out})$$

$$805 \frac{kJ}{s} = 38.11 \frac{kg}{s} * 3718 \frac{J}{kg * K} * (T_{hot,in} - 358K)$$

$$805000 \frac{J}{s} = 38.11 \frac{kg}{s} * 3718 \frac{J}{kg * K} * (T_{hot,in} - 358K)$$

$$5.68K = T_{hot,in} - 358K$$

$$T_{hot,in} = 363.7K$$

Cold Water Flow Rate

Due to the engine not producing as much heat as the heat exchanger is rated for, the cooling capacity is required to be decreased and the cold-water flow rate reduced.

To find the mean temperature:

$$\dot{Q} = U * A_s * \Delta T_m$$

$$805000W = 1700 \frac{W}{m^2 \cdot K} * 18.51 \text{ m}^2 * \Delta T_m$$

$$\Delta T_m = 25.58K$$

Using the log mean temperature difference:

$$\Delta T_{lm} = \frac{\Delta T_1 - \Delta T_2}{\ln\left(\frac{\Delta T_1}{\Delta T_2}\right)}$$
$$25.58K = \frac{\Delta T_1 - \Delta T_2}{\ln\left(\frac{\Delta T_1}{\Delta T_2}\right)}$$

Understanding:

$$\Delta T_1 = T_{hot.in} - T_{cold,out}$$
$$\Delta T_1 = 363.7K - T_{cold,out}$$

And:

$$\Delta T_2 = T_{hot.out} - T_{cold,in}$$
$$\Delta T_2 = 358K - 318K$$
$$\Delta T_2 = 40K$$

Substituting back in:

$$25.58K = \frac{368.7K - T_{cold,out} - 60K}{\ln\left(\frac{368.7K - T_{cold,out}}{60K}\right)}$$
$$25.58K = \frac{308.7K - T_{cold,out}}{\ln\left(\frac{368.7K - T_{cold,out}}{60K}\right)}$$

This is not solvable algebraically, so excel solver module was used to optimise the data and find a result using an iterative method. The initial data was entered as per figure 5-3 with the cold-water outlet estimated at 360K. The solver was run with target of T_mean value of 25.58 changing the cold-water outlet value. The solution can be seen in figure 5-4.

Known			Intermedi	ate Values
Hot Water Outlet	358		T_1	3.7
Hot Water Inlet	363.7		T_2	40
Cold Water Inlet	318]		
Unknown		l	Out	puts
Cold Water Outlet	360		T_mean	15.2486



100	Interme	diate Va
358	T_1	15.1
363.7	T_2	4
318		
	358 363.7 318	358 T_1 363.7 T_2 318 T_2

Figure 5-4: Solved values in Excel.

 $T_{cold,out} = 348.57K$

The cold-water flow rate was found using:

$$\dot{Q} = \dot{m}_c c_{p,c} (T_{cold,out} - T_{cold,in})$$

$$805kW = \dot{m}_c * 4180 \frac{J}{kg * K} (348.57K - 303K)$$

$$\dot{m}_c = \frac{805000 \frac{J}{s}}{4180 \frac{J}{kg * K} (348.57K - 303K)}$$

$$\dot{m}_c = 4.23 \frac{kg}{s}$$

Converting to volumetric flow rate:

$$\dot{m_c} = \dot{V_c} * \rho_c$$
$$\dot{V_c} = \frac{\dot{m_c}}{\rho_c}$$
$$\dot{V_c} = \frac{4.23 \frac{kg}{s}}{990.1 \frac{kg}{m^3}}$$
$$\dot{V_c} = 0.0043 \frac{m^3}{s}$$

Control Valve Angle

To use a mathematical equation to calculate the flow rate by valve angle, pressures that are unknown to industry equipment would need to be known. The chart in figure 5-5 (Johnson Controls, 1996), was used to estimate the valve position.



Figure 5-5: Valve flow rate percent vs valve opening percentage (Johnson Controls 1996).

With the valve fully open, the system required a flow rate of $0.020 \frac{m^3}{s}$ and at operating conditions the system flow rate required to maintain the desired temperatures dropped to $0.0043 \frac{m^3}{s}$. This results in a flow of 21.5% of the pump capacity. Using the chart in figure 5-7 the approximate valve position will be 50° from fully closed.

5.5 Global Distribution model

Experiments 1 to 3 for chapter 5 CFD modelling was completed on the complete heat exchanger system to see if the addition of the valve influences the global temperature distribution.

5.5.1 Model Creation

3D Model

As the model was significantly larger in size compared to earlier models it was created as one continuous dual wall shape with a right-angle entry point for the cold-water entry to reduce the elements required. The tube was created with 5 bends to keep the shape in a length/width ratio ideal for viewing for analysis on a screen. The five bends were created with 2m radius giving 3.14m of transfer length each. Each of the 6 main lengths was therefore created at 8.88m of length to get the total required length of 69m.

All bends were created with radii or simple corners to sweep each part without sharp corners. A valve was created in the cold-water entry region with 0.14m outside diameter, 0.02m thickness and 0.004m chamfers. The cold-water domain was created by making a subtractive Boolean and the three resulting parts combined to make one part.



Figure 5-6: 3D Model for the scaled model.


Figure 5-7: Valve in the entry region of scaled model.

Mesh and Named Selections

The mesh was created using a similar method to the model from section 4.2.2 and 4.4.2. It was created using a 2800 division sweep mesh through the hot-water domain, 0.035m body tetrahedron mesh in the cold-water domain and finer face mesh around the valve body. The setup was refined until a final element count of 400,987 elements was obtained, understanding that some free elements would be needed for the conductive shell transfer wall generated by Fluent. Due to the size of the model, it was difficult to create a stable mesh for this part that stayed under the 512,000-element limit of the ANSYS student version so a mesh independence study was no completed for this model. These results are presented with the understanding that this mesh independence study was not performed to verify the data is reliable.



Figure 5-8: Exterior view of the mesh elements for the global model.



Figure 5-9: Sectioned view of the mesh elements for the global model.

The named selection choice was refined from the earlier model to a more simplified model without losses from convection. The following areas of the model were named:

- All external walls were named as insulation walls
- all internal walls were named as transfer walls
- the inlets and outlets
- the cold-water and hot-water domains.

Fluent Setup

The model was setup with material properties as per table 5-2 below.

Material	Density	Specific Heat	Thermal	Viscosity	Source
	(kg/m^3)	(J/(kg K)	Conductivity	(kg/(m s)	
			(W/(m K)		
Water @ 20°C	998.2	4182	0.6	0.001003	ANSYS
					Library
50/50	1030	3690	0.6	0.0007	(Engineering
Glycol/Water					ToolBox 2013)
mixture @					- interpolated
93.3C					
Stainless Steel	7900	477	14.9	N/A	(Cengel &
					Ghajar 2015)

Table 5-2: Scaled model material properties.

The model was setup with the boundary condition as per table 5-3 below.

Table 5-3: Scaled model boundary conditions.

Parameter	Value
Hot Water In	363.7 K
Hot Water Mass Flow	38.11 kg/s
Cold Water In	318 K
Cold Water Mass Flow	4.23 kg/s

The model was setup with the parameters and settings as per table 5-4 below.

Table 5-4: Scaled model	parameter setup.
-------------------------	------------------

Area	Parameter	Comments
Setup – Models	Energy Equation	Turned on
		k-epsilon
Setup – Models	Viscous Model	Realizable
		Enhanced Wall Treatment
Setup – Materials	Fluids	Water-liquid and coolant setup
Setup – Materials	Solids	Steel-stainless setup
Satur Call Zona	Cold water domain	Cold Water as fluid – water-liquid
Setup - Cell Zolle	Hot water domain	Hot Water as fluid – coolant
Conditions	Valve domain	Valve domain as acrylic
Setup - Boundary	Hot water out	Setup as pressure outlets (better
Conditions	Cold water out	results than mass flow in this case)
		Setup as mass flow inlet
Setup - Boundary	Hot water in	Setup flow rate as normal to
Conditions	Cold water in	boundary with flow rate and
		temperature as per table 5-3
Setup - Boundary	Insulated Wall – Cold water domain	Satur as no heat transfer
Conditions	Insulated Wall – Hot water domain	Setup as no near transfer
		Setup as coupled transfer with the
Setup - Boundary	Transfer well	shadow equivalent. Setup as single
Conditions		layer stainless shell conduction
		with wall thickness of 0.004m
Setup - Boundary	Cold water domain to valve well	A amplia with no heat transfor
Conditions	Cold water domain to valve wan	Actylic with no near transfer
Solution – Method	Scheme	Coupled
Solution – Monitors	Residuals	All changed to 1E-06
Solution – Initialization	Method	Hybrid Initialization
Run Calculation	Number of Iterations	600

Initial Calculations and Verification

For the initial calculations and verification, the model was adjusted to remove the valve in the inlet. This allowed for a baseline model to be created and validation of the model compared to the mathematical model in section 5.4.

The stainless-steel material conduction transfer rate parameters and calculations were adjusted multiple times until the outlet temperatures matched the mathematical model. This step was necessary as some parameters could not be directly transferred to the CFD model, an example being the overall heat transfer coefficient. Table 5-5 shows the final outlet temperatures compared between the mathematical model and the CFD model. It was found after many configuration changes, the model could not be configured to perfectly match the mathematical model. It is the author's thoughts that this is a problem with the meshing in the model. Due to the size of the model and the fine size of the mesh it is not possible within the limits of the modelling to correctly model this scenario.

Parameter	Mathematical Model	CFD Model	Error
Cold Outlet	348.57 K	349.10 K	0.15%
Hot Outlet	358.00 K	358.91 K	0.25%

Table 5-5: Comparison of mathematical vs CFD model outlet temperatures.



The residuals were inspected and show that the results converged as seen in figure 5-17 below.

Figure 5-10: Residuals for the scaled global model without valve.

The mass flow rate was checked to ensure the two fluid paths did not mix and no other major problem were evident in the CFD model as shown in figure 5-11.

Mass Flow Rate	(kg/s)
cold_inlet	4.23
cold_outlet	-4.2300272
hot_inlet	38.11
hot_outlet	-38.11
Net	-2.7230147e-05

Figure 5-11: Mass Flow Rates of the scaled global CFD model without the valve.

A plane cut was made through the X-Z axis and a temperature contour plot made. The temperature contours show the continual cooling of the hot water and heating of the cold water expected to see in this arrangement. The contour was inspected for any unintentional mixing of the two fluids or any other unusual or unexpected results. The heat distribution in the cold-water domain was seen to vary significantly more than the model from section 4.2 due to the higher temperature difference.



Figure 5-12: Temperature distribution of the scaled global CFD model without the valve.

5.5.2 Analysis

The model was updated to have valves in both the realistic case (49.5°) and extreme case (25°) scenarios. The meshing process and calculations were run again to get data for these two scenarios.

Several cuts were made in the result modules across the cold and hot domains at various points through the heat exchanger. The chosen measurements points were at equal positions throughout the exchanger core. The

temperatures results were collected using the function calculator: mass-weighted average method. The results were tabulated (table 5-6) and plotted (figure 5-13) to see if there was any notable difference between scenarios.

				Location			
	0	1	2	3	4	5	6
Hot Water - No Valve	363.7	363.22	362.661	362.059	361.21	360.119	358.906
Cold Water - No Valve	318	328.006	335.876	343.06	347.818	348.699	349.097
Hot Water - 49.5°	363.7	363.225	362.663	362.059	361.211	360.124	358.891
Cold Water - 49.5°	318	328.102	335.975	343.06	347.832	348.737	349.14
Error - 49.5°	0.00%	-0.01%	-0.01%	0.00%	0.00%	-0.01%	0.00%
Hot Water - 25°	363.7	363.224	362.661	362.057	361.21	360.122	358.883
Cold Water - 25°	318	328.045	336.025	343.105	347.86	348.678	349.113
Error - 25°	0.00%	-0.01%	-0.02%	-0.01%	-0.01%	0.00%	0.00%

 Table 5-6: Results of global temperature distribution at various valve angles.



Figure 5-13: Global temperature distribution at various valve angles.

5.5.3 Findings

These results indicate no influence from the control valve on the global temperature distribution throughout the heat exchanger core.

5.6 Local Distribution Model

CFD modelling was completed on the entry region of the heat exchanger to see if the addition of the valve influences the local temperature distribution.

5.6.1 Model Creation

3D Model

The entry region model was created in a similar way to the model from section 4.5. The main transfer region was created with a length of 1.5m to have a length of approximately 10x the valve diameter. A valve was created in the cold-water entry region with 0.14m outside diameter and 0.02m thickness and 0.004m chamfers. The cold-water domain was created by making a subtractive Boolean and the three resulting parts combined to make one part.



Figure 5-14: 3D model for the entry region scaled model.



Figure 5-15: Valve in the entry region of scaled model.

Mesh and Named Selections

The mesh was created using a similar method to the model in section 4.5 using a swept mesh for the hot-water domain and 0.008m body tetrahedron mesh in the cold-water domain with finer face mesh around the valve body. The setup was refined until a final element count of 407,185 elements was achieved, without the valve, with the understanding free elements will be needed for the conductive shell transfer wall generated by Fluent.



Figure 5-16: Initial mesh for the entry region scaled model.

The named selections were refined from the earlier model to be a simplified model without losses from convection. The following areas of the model were named:

- All external walls were named as insulation walls
- All internal walls were named as transfer walls
- The inlets and outlets
- The cold-water and hot-water domains.

Fluent Setup

The model was setup with material properties as per table 5-2 in section 5.5.1. To get the entry condition of the hot water, a plane was created on the global model from section 5.5, 1.5 from the tube beginning shown in table 5-7.

Parameter	Value
Hot Water In	359.11 K
Hot Water Mass Flow	38.11 kg/s
Cold Water In	318 K
Cold Water Mass Flow	4.23 kg/s

Table 5-7: Scaled entry region model boundary conditions.

The model was setup in Fluent as per table 5-8 below. Note in this section the \mathbf{k} - $\boldsymbol{\varepsilon}$ turbulence model was used even though the \mathbf{k} - $\boldsymbol{\omega}$ model was found more accurate in section 4.5. In this case with multiple experiments performed, the \mathbf{k} - $\boldsymbol{\varepsilon}$ model was found to converge an order of magnitude lower and show more realistic turbulence results.

Area	Parameter	Comments	
Setup – Models	Energy Equation	Turned on	
		k-epsilon	
Setup – Models	Viscous Model	Realizable	
		Enhanced Wall Treatment	
Setup – Materials	Fluids	Water-liquid and coolant setup	
Setup – Materials	Solids	Steel-stainless setup	
Satur Call Zona	Cold water domain	Cold Water as fluid – water-liquid	
Conditions	Hot water domain	Hot Water as fluid – coolant	
Conditions	Valve domain	Valve domain as acrylic	
Setup - Boundary	Hot water out	Setup as pressure outlets (better	
Conditions	Cold water out	results than mass flow in this case)	
		Setup as mass flow inlet	
Setup - Boundary	Hot water in	Setup flow rate as normal to	
Conditions	Cold water in	boundary with flow rate and	
		temperature as per table 5-24	
Setup - Boundary	Insulated Wall – Cold water domain	Setup as no heat transfer	
Conditions	Insulated Wall – Hot water domain	Setup as no near transfer	
		Setup as coupled transfer with the	
Setup - Boundary		shadow equivalent. Setup as single	
Conditions	Transfer wall	layer steel-stainless shell	
Conditions		conduction with wall thickness of	
		0.004m	
Setup - Boundary			
Conditions	Cold water domain to valve wall	Acrync with no neat transfer	
Solution – Method	Scheme	Coupled	
Solution – Monitors	Residuals	All changed to 1E-06	
Solution – Initialization	Method	Hybrid Initialization	
Run Calculation	Number of Iterations	500	

Table 5-8: Scaled model p	parameter setup
---------------------------	-----------------

Initial Calculations and Verification

To validate this model, the boundary conditions were compared to the values from the global model in section 5.5. The error as per table 5-9 was found to be insignificant, validating the model.

Parameter	Global Model	Entry-Region Model	Error
Cold Outlet	319.92 K	319.82K	0.031%
Hot Outlet	358.91 K	358.88K	0.001%

Table 5-9: Comparison of mathematical vs CFD model outlet temperatures.

The residuals were inspected and show that the results converged as seen in figure 5-17 below.



Figure 5-17: Residuals for the scaled entry region model without valve.

The mass flow rate was checked to ensure the two fluid paths did not mix and no other major problems were evident in the CFD model as shown in figure 5-18.

Mass Flow Rate	(kg/s)
cold_inlet cold_outlet hot_inlet hot_outlet	4.23 -4.2300038 38.11 -38.11
Net	-3.7751514e-06

Figure 5-18: Mass flow rates of the scaled entry region CFD model without the valve.

Mesh Independence Study

Since many computations are to be performed, a mesh independence study was conducted to find a mesh size suitable to acquire accurate calculations whilst minimizing computation time to complete the study. To complete this study, 17 fluent studies were run with various mesh sizing and the results tabulated.

Four resulting categories were reviewed and compared.

- Convergence Error Representation: Each study was compared to the baseline for the X,Y&Z velocity, continuity equation and energy equation residuals. To compare to the baseline, any value larger than the baseline was averaged and compared to the baseline in percentage error
- Outlet Temperatures: The outlet temperatures of both the hot and cold domains were compared to the baseline as a percentage error
- Wall Pressure: The wall pressure of the hot and cold domains 75mm from the start of the main tube was compared to the baseline as a percentage error
- Mass Flow Rate: The mass flow rate of the hot and cold domains 75mm from the start of the main tube was compared to the baseline as a percentage error
- Element Reduction: Each study was compared to the based for the total elements generated through the mesh setup. The mesh was compared to the baseline using a percentage
- A subject visual inspection of the streamlines around the valve and following the sharp corner was also performed to ensure no unusual results were being missed at lower mesh element counts.

The full results of the mesh independence study can be found in Appendix H. The resulting elements were plotted against the dependant variables to determine if the study was mesh dependant. Analysis of the results in figure 5-19 below shows that the results are mesh dependant and stability is achieved with a mesh count of approximately 375,000 elements.



Figure 5-19: Mesh Independence Study results showing stability after approximately 375,000 elements.

Since this is not significantly reducing the elements amount and accuracy is important for this study, the mesh was left at the max element settings.

Hot water Domain:

- Method: Sweep mesh, using hot water entry face as source and outlet as the target
- Mesh Type: All Quad
- Edge Divisions: 36
- Bias: No Bias.

Hot water Domain:

- Method: Tetrahedrons
- Body Sizing: 0.008m.

Resulting Mesh: 452,359 elements.

5.6.2 Analysis

The model was updated to have valves in both the realistic case (50°) and extreme case (25°) scenarios. The meshing process and calculations were run again to get data for these two scenarios.

Cross-section cuts were made through the CFD models with and without the valve. The lowest, highest, and average temperatures were analysed. As the heat distribution is likely to be most affected closest to the valve, cuts were made every 10mm for the first 150mm, 20mm for the next 150mm and 50mm up to 490mm from the cold-water domain start wall. As the fouling is most likely to occur in the hot water side, the measurements were taken by creating the cut with a radius of 0.055m, in the cold-water domain, resulting in a sample close to the transfer wall as shown in figure 5-20 below.



Figure 5-20: Example of sample cut to measure min, max and average temperature close to transfer wall.

To get the data values, the function calculator in the ANSYS results module was used at each cut location for each of the models. For maximum temperature the "maxVal" function was used, for minimum temperature the "minVal" function was used, and for average temperatures the "massFlowAve" function was used.

The ANSYS experiments were completed, the data tubulised and can be seen in full in appendix G. Figure 5.-21 shows the minimum temperatures in the wall region for each model. This data shows little variation in minimum temperature with less than 1 degree difference at any location along the test length. Figure 5-22 shows the maximum temperatures in the wall region for each model. This data shows significant variation between the model without a valve and the two models with valves. This data is reviewed and discussed in more detail later in this section. Figure 5-23 shows the average temperature in the wall region for each model. This data shows very little variation in the average temperatures between each model. Some temperature variations can be seen between the model with the valve and the two models without a valve, however it is erratic and does not show a trend.



Figure 5-21: Minimum temperature at the transfer wall region at various valve positions.



Figure 5-22: Maximum temperature at the transfer wall region at various valve positions.



Figure 5-23: Average temperature at the transfer wall region at various valve positions.

Figure 5-22 shows the maximum temperatures fluctuate significantly in the first 250mm of tube between the different models with the temperature trend lines crossing each other and not showing any notable trend. This is shown in more detail in figure 5-24 below. In the section 250 - 475mm from the starting wall, the temperature trend lines on the two models with the valve can be seen to trend significantly above the baseline trend line. This is shown in more detail in figure 5-25 below.



Figure 5-24: Maximum temperature at the transfer wall region at various valve positions refined for 0-250mm.



Figure 5-25: Maximum temperature at the transfer wall region at various valve positions refined for 250-500mm.

In both models the maximum temperature trend lines trend 2-4 degrees above the baseline trend line between the distances of approximately 275-425mm from the hot water exit point.

5.6.3 Findings

This section analysed the entry region of the heat exchanger comparing CFD models of a heat exchanger scaled to an industrial application with and without a valve. The data has shown that when the valve angle is closed to significantly change the flow rate of the fluid there is higher maximum temperatures on the transfer wall between 275-425mm into the tube's transfer wall region.

This was noted to produce similar results to those produced on the Armfield models in section 4.5, however at different locations. It was also noted that the entry region and valve geometry was significantly different between the Armfield and scaled models with 8.25mm diameter valve compared to 140mm diameter valve. To investigate this further, the two datasets were normalised by changing the distance to a scale of units of valve diameter to compare. The extreme valve closed cases from section 4.5 and 5.6 were used for clarity. The plot of these results can be seen in figure 6-1 below.



Figure 5-26: Maximum temperature at transfer wall by units of valve diameter.

Both the Armfield and scaled models have shown a significant deviation in the temperature trend lines at a location between approximately 1.9 and 2.9x the diameter of the entry region into the heat exchanger.

These two experimental datasets combined gives the author confidence these findings are valid. There is genuine influence from the valve on the maximum temperature spikes found on the transfer wall in the entry to the head exchanger.

5.7 Valve Angle Influence

The results discussed in both section 4.5.6 and 5.6.3 have shown deviations from the baseline (no valve) transfer wall temperature distribution can be caused from the control valve. For further verification and to understand if the valve angle had an influence on the amount of temperature spikes experienced, further studies were completed on the area 210-550mm from the starting wall on the scaled model.

The existing model, meshing and boundary conditions from chapter 5.6 were used. For finer resolution, measurement spacing was changed to collect 18 sets of data through the 210-550mm section of interest identified in the previous section resulting in 20mm spacing between measurements.

The full set of tubulised data from these experiments can be found in appendix I. Figure 5-26 below shows the maximum temperature at the transfer wall at various locations for valve opening positions at every 5° angle. To give a more clarity, the data was smoothed by averaging each reading with the previous and following values.



Figure 5-27: Maximum temperature at transfer wall for various valve open angles (smoothed).

This graph whilst busy, shows that in general all the models with the valve trend higher than the baseline through the 200-400mm region. Between the 400-520mm region of the graph some temperature trend lines stayed higher than the baseline, however some trended under. The more-closed valves appear to have higher deviations from this chart.

To investigate this further, the temperature differences for each valve open position was averaged and the maximum deviation was calculated. This data was plotted as shown in figure 5-27 below. The general trendlines show that as the valve is closed, the maximum temperature spikes on the transfer wall increase in both on average across the region and in maximum value measured.



Figure 5-28: Average and maximum temperature differential with various valve open angles.

6.0 Chapter 6: Conclusion

6.1 Findings and Discussions

This dissertation set out to investigate the claims that a variable speed pump used in heat exchanger control system would create a better heat distribution throughout the exchanger, compared to a fixed output pump with butterfly control valve at the process water entry point.

ANSYS Computational Fluid Dynamics software was used to analyse a series of 3D models of fluid paths within a dual tube heat exchanger. The initial simple models were verified with physical experiments. Subsequent models were then created with greater complexity and size and verified with models. The initial models were created to simulate the Armfield HT36 educational heat exchanger at the University of Southern Queensland. Subsequent models were scaled and modified to simulate the conditions of an industrial application.

In both the smaller and scaled models and simulations, two hypothesises were tested:

- If an entry region control valve would influence the global temperature distribution of fluids within the heat exchanger
- If an entry region control valve would influence the local temperature maximums on the transfer wall of the heat exchanger close to the entry region.

Following these findings, a third hypothesises was tested as further work to further validate the results:

• If there was a valve angle which would produce the maximum temperature spike.

Global Temperature Distribution

In section 4.4, the global temperature distribution was compared across the whole Armfield HT36 heat exchanger core in both physical and CFD experiments. The physical experiments found a temperature difference of 0.31% and a difference of 0.55% in the boundary conditions. The CFD experiments found an error of 3.51% and the same 0.55% difference in the boundary conditions. The CFD models however revealed a departure in boundary conditions compared to previous models when the value was added. This is likely due to some slight differences in meshing required and boundary conditions in the model.

In section 5.5, the global temperature distribution was compared across a scaled model of a heat exchanger with the sizing, fluid and boundary conditions changed to match the requirements of an industrial application. These CFD experiments showed a maximum error of 0.02% between models for all the measurement locations across the model heat exchanger.

The combination of these tests gives the author confidence that a control valve near the entry region of the heat exchanger has no influence on the global temperature distribution throughout the heat exchanger.

Local Transfer Wall Maximum Temperatures

In section 4.5, a CFD model was created isolating the entry region of the Armfield HT36 heat exchanger to investigate influence of a valve on the transfer wall area. The experiments with a valve at a significantly closed position revealed maximum temperature trend lines that deviated from the baseline trend line. This occurred between 15 and 25mm from the hot water exit wall. The variation was between 3-4 degrees through this region.

In section 5.6, a similar experiment was performed with a scaled model of a heat exchanger with the sizing, fluid and boundary conditions changed to match the requirements of an industrial application. Like the first experiment, this CFD modelling found the maximum temperature trend lines that deviated from the baseline trend line by 2-4 degrees. This was noted to be at 275 to 425mm from the hot water exit wall.

In section 5.6.3 the results from section 4.5 and 5.6 were compared by dividing the data location into the exchanger by the valve diameter. Comparing the results found the temperature spikes occurred at the same relative location of 1.9-2.9x the valve diameter into the heat exchanger.

The combination of these tests gives the author confidence that a control valve near the entry region of the heat exchanger does have influence on the local temperature distribution at the transfer wall of the heat exchanger.

Valve Angle Influence

In section 5.7 a series of computational fluid dynamic experiments were completed on the scaled heat exchanger model with valves in various open positions incrementing by 5° each experiment. These results of this data showed the temperature spikes generally increased as the valve was further closed. This set of data also reinforced the findings about the local transfer wall discussed above with the experiments with the valve showing temperatures spikes above the baseline.

6.2 **Recommendations**

In chapter 1 it was discussed that this project was inspired by the sales pitch of a supplier indicating their heat exchanger product was better due to the use of variable speed pumps instead of butterfly control valves. Based on the findings of this dissertation the author agrees it is possible the use of a control valve could create hot locations within the transfer wall region of the heat exchanger core. Possible mitigation to these localised hot locations could be:

- The removal of the control valve through a variable speed pump
- Relocation of the control valve to more than 10x valve diameter away from the entry region.

Aside from the findings in this study, the use a variable speed pump does have the other benefits:

- Efficiency improvements from using less power when variable speed pump has less output
- Longer pump life due to less cavitation from the throttling affect.

6.3 Further Work

As discussed in section 3.2.2, the technology used in most industrial application is not dual-wall type heat exchangers but often plate-type heat exchangers. To verify the results of this study for industrial equipment, this study should be repeated with real models of equipment. This would likely require sponsorship of a supplier as the geometry of such equipment would likely be proprietary.

The mesh in section 5 had to be coarser than the author would have liked due to the element limitation of ANSYS student edition. Further work could be done to complete a mesh independency study on the models from this section using a full version of ANSYS to verify the results are stable and accurate. In the literature review section 2.4.2, it was found other available studies required element counts of >3,000,000 elements for stability where the use of ANSYS student version in this study limited the models to 512,000 elements.

A further study could be completed on the temperature trend deviation found between 1.9 and 2.9x the entry region diameter to understand if and how the deviation varies at different entry temperatures, geometry, and valve angles. The scope of these experiments would be unfeasible within this dissertation as it would likely involve many hundreds of experiments of considerable analysis. It would be interesting to further study what combination of temperature difference, valve angle, valve geometry and heat exchange geometry causes the most affect to the local temperature spikes. The CFD study could also be refined to include more data points in the region identified to be most affected.

The temperature differences found in the heat exchanger transfer wall were on 3-4 degrees. Further work could be completed to understand what level of temperature spikes on the transfer wall would lead to undesirable effects such as fouling and nucleate boiling.

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Appendix A – Project Specification

For:	Terrence Clarke
Title:	Heat exchanger performance and optimization
Major:	Mechanical Engineering
Supervisor:	Khalid Saleh
Enrollment:	ENG4111 – ONC S1, 2021
ENG4112 – ONC S2, 2	2021
Project Aim:	To understand if, in an engine dynamometer test cooling application, using a fixed output water pump with butterfly valve produces localized hot spots in a fluid to fluid heat exchanger core compared to the use of a variable speed water pump without control valve.
Confidentiality:	All information used for the project will be based on information available in the public domain, so will not require any specific confidentiality consideration. During the information gathering stage, if I find I need specifications outside the public domain I will work with USQ and supplier of information to consider if public access restriction is appropriate.
Communication Plan:	Weekly update emails from Terrence to Khalid. Zoom calls or face-to-face meetings as/if required at time agreed by both parties.

Programme: Version 1, 18 March 2021

- 1. Research existing studies and literature available on temperature distribution throughout a head exchanger, comparing the use of throttling valves vs variable speed pump control systems.
- 2. Research industrial heat exchangers available for dynamometer testing of a large diesel engine.
- 3. Research information on the USQ laboratory fluid/fluid heat exchanger.
- 4. Learn how to complete a CFD study of heat exchanger using Ansys software.
- 5. Complete initial CFD studies using boundary conditions that could be simulated in the lab environment.
- 6. Complete physical experiment in the USQ lab with same boundary conditions as CFD studies. Compare results and confirm CFD and physical experimental data match.
- 7. Re-scale the CFD simulation to a set of real-life boundary conditions and complete a series of studies.
- 8. Analyse data and produce conclusion.

Appendix B – Project Planning Timeline

0	Task Mode +	Task Name 👻	Duration	- Start -	Finish .	. Pe .	Resource Names	• Actual Finish •	Qt/ 1, 2021 Jan	Fet			Mar	Qtr 2, 2021 Apr	May	Jun	Qtr 3, 2021 Jul	Au	9	Se	Qtr 4, 200	in ci
1	-	 Project Approval 	6 days	Mon 1/02/21	Mon 8/02/21			Mon 8/02/21														
~	*	Submit Project Proposal	4 days	Mon 1/02/21	Thu 4/02/21			Thu 4/02/21		100		•										
~	*	Approval	2 days	Fri 5/02/21	Mon 8/02/21	2		Mon 8/02/21		iii ii												
		 Project Specification 	18 days	Mon 22/02/21	Wed 17/03/21			NA			-	-										
	*	Create Project Specification 1-pager	11 days	Mon 22/02/21	Sun 7/03/21			NA			1											
	*	Create Project timeline	11 days	Mon 22/02/21	Sun 7/03/21			NA														
	*	Create Project Resources	11 days	Mon 22/02/21	Sun 7/03/21			NA														
	*	Get draft agreement from Supervisor	6 days	Mon 8/03/21	Sun 14/03/21	5,6,	7	NA	1			-	1									
-	*	Submit	3 days	Mon 15/03/21	Wed 17/03/21	8		NA	1				is.									
-	-	Research	133 days	Mon 1/03/21	Wed 1/09/21			NA				-			 	 		 		i		
	-3	 Dissertation and Presentation 	108 days	Mon 17/05/21	Wed 13/10/21			NA								 		 				

Figure B-1: Screenshot of project plan showing project approval and project specification plans.

0	Task Mode -	Task Name	Duration	- Start -	Finish +	Pi - Resource Names	- Actual Finish -	Qtr 1, 2021 Jan	eb	Mar	Qtr 2, 2021 Apr	May	Jun	Qtr 3, 2021 Jul	Aug	Seg	Qtr 4, 2021 Oct
~	10. july	Project Approval	6 days	Mon 1/02/21	Mon 8/02/21		Mon 8/02/21										
-	-	Project Specification	18 days	Mon 22/02/21	Wed 17/03/21		NA	4		1							
	-	4 Research	133 days	Mon 1/03/21	Wed 1/09/21		NA	1	r							-	
	*	Self-learn CFD - ansys	36 days	Mon 1/03/21	Sat 17/04/21		NA										
	*	Literature Review	45 days	Mon 1/03/21	Fri 30/04/21		NA										
	*	Research of engine dyno application	45 days	Mon 1/03/21	Fri 30/04/21		NA		- 2								
	*	Source information about USQ heat exchanger	45 days	Mon 1/03/21	Fri 30/04/21		NA		1								
	*	Complete initial CFD study for USQ heat exchanger	11 days	Sat 17/04/21	Fri 30/04/21		NA										
	*	Scope out physical experiement tooling requirements	12 days	Sat 1/05/21	Sat 15/05/21		NA										
	*	Create physical experiement plan	5 days	Sun 16/05/21	Thu 20/05/21		NA	ē				101					
	*	Complete physical experiements	5 days	Mon 21/06/21	Fri 25/06/21		NA						100				
	*	Compare CFD and physical experiement results	12 days	Sat 26/06/21	Sat 10/07/21		NA										
	*	Re-scale CFD studies to match the real-life boundary conditions and size	32 days	Sun 11/07/21	Sat 21/08/21		NA										
	*	Analyse data and generate conclusions	9 days	Sun 22/08/21	Wed 1/09/21		NA										
	-	Dissertation and Presentation	108 days	Mon 17/05/21	Wed 13/10/21		NA					-			 		



0	Task Mode 🐱	Task Name 🗸	Duration •	- Start	Finish 👻	Pr+ N	source imes v	Actual Finish 🐱	Qtr 1, 2021 Jan	14	Feb	Mar	Qtr 2, 2021 Apr	May	Jun	Qtr 3, 2021 Jul	Aug	Sep	Qtr 4, 2021 Ort
~	mg.	Project Approval	6 days	Mon 1/02/21	Mon 8/02/21			Mon 8/02/21											
	-	Project Specification	18 days	Mon 22/02/21	Wed 17/03/21			NA			- F								
		> Research	133 days	Mon 1/03/21	Wed 1/09/21			NA				· · · · ·					 	٦	
	-	 Dissertation and Presentation 	108 days	Mon 17/05/21	Wed 13/10/21			NA						·			 		_
	*	Write-up progress report	t 6 days	Mon 17/05/21	Sat 22/05/21			NA						-					
	*	Submit Progress report	3 days	Mon 24/05/21	Wed 26/05/21			NA						10					
	*	Compile Partial Dissertation	42 days	Sun 11/07/21	Sun 5/09/21			NA											
	*	Submit Partial Dissertation	3 days	Mon 6/09/21	Wed 8/09/21			NA										10	
	*	Compile Presenation	8 days	Thu 9/09/21	Sun 19/09/21			NA											
	*	Present Presenation	5 days	Mon 20/09/21	Fri 24/09/21			NA										100	1 E
	*	Finalise Dissertation	23 days	Thu 9/09/21	Sun 10/10/21			NA											
	*	Submit Dissertation	3 days	Mon 11/10/21	Wed 13/10/21			NA											105

Figure B-3: Screenshot of project plan showing dissertation and presentation plans.

Appendix C – Risk Assessment for Physical Experiments

This risk assessment was completed on, and approved in, the USQ Safety Risk Management System online system. Screenshots showing all the detail are in this appendix.

University of	Southern Queensla	nd		Read Only View
UNIVERSITY ef southern QUEENSLAND USQ Safet	y Risk Manage	ment Syster	n	
Close				Develop as new RMP
				Version 2.0
	Safety Risk Mar	nagement Plan		
Risk Management Plan ID: Status: RMP_2021_5546 Approve	Current User:	Author:	Supervisor:	Approver:
Assessment Title: Armfield HT36 Exper	iment for Terrence Clarke ENG4111	L Dissertation	Assessment Date:	19/05/2021
Workplace (Division/Faculty/Section) 204070 - School of M	lechanical and Electrical Engineerin	ne	Review Date:	31/12/2021
				(5 years maximum)
Approver:		Supervisor: (for notification	on of Risk Assessment only)	
Khalid Saleh;	₹v 💷	Mohan Trada;		₹ ₂ /
DESCRIPTION:	Com			
What is the task/event/purchase/project/procedure?	Complete the Armfield HT36 E	Experiments as per experime	nt plan provided.	
Why is it being conducted?	Experimental data for ENG411	11 dissertation		
Where is it being conducted?	USQ Lab			
Course code (if applicable)	ERP2021/ENG4111	Chemical N	ame (if applicable)	Water
WHAT ARE THE NOMINAL CONDITIONS?				
Personnel involved	Terrence Clarke (student), Kha	alid Saleh (Supervisor) & Mol	han Trada (Technical Staff)	
Equipment	Armfield HT36 test equipmen	nt		
Environment	Lab			
Other	Estimated Experiment Date: N	Monday 24 May 2021.		
Briefly explain the procedure/process	Performing Experiement A fro water through a heat exchange	om the Armfield HT36 instruc ger test jig and logging tempe	tion manual and recording the d aratures through existing thermo	ata. This involves running cool and warm couples.
Assess	ment Team - who is c	onducting the ass	essment?	
Assessor(s):	Khalid Saleh (Supervisor), Be	elal Yousif (Examiner)		
Others consulted: (eg elected health and safety representative, other personnel exposed to risks)	Mohan Trada (Technical Staf)	ฮ)		

Figure C-1: Risk assessment header information.

				Risk Regist	ter and a	Analys	is						
	Step 1	Step 2	Step 2a	Step 2b		Step 3			Step 4				
	Hazards: From step 1 or more if identified	The Risk: What can happen if exposed to the hazard without existing controls in place?	Consequence: What is the harm that can be caused by the hazard without existing controls in place?	Existing Controls: What are the existing controls that are already in place?	Risk /	Assessmen Probability - I	IŻ: Risk Level	Additional Controls: Enter additional controls if required to reduce the risk level	Risk asse	essment wit controls sequence or pro	th additions : bability char	onal nged?	
					Probability	Risk Level	ALARP		Consequence	Probability	Risk Level	ALARP	
	Example												
	Working in temperatures over 35 ⁰ C	Heat stress/heat stroke/exhaustion leading to serious personal injury/death	catastrophic	Regular breaks, chilled woter available, loase clothing, fatique management palicy.	passible	high	No	temporary shade shefters, essential tasks only, close supervision, buddy system	catastrophic	unlikely	mod	Mes	
1	Unidentified risks due to lack of familiararity of the equipment	Personal or equipment/facili ty damage	Moderate 💙	Nil	Possil 💙	High		Review of the Armfield HT36 manual and the task specific USQ Risk	Minor 🗸	Ran 🗸	Low	1	
2	Injury from high temperature fluid contacting human	Eye damage Skin burns	Major 🗸	Eye protection is mandatory in the lab Experimental jig has been designed with a maximum temperature of 80DegC	Unlik 🗸	Med		Dissertation experiement designed to use approx 50DegC maximum Temperature. Flow cold water through experiement first to ensure no leaks or loose fittings. Experiemental equipment not to be opened by student - seek technical assistance if faults found.	Minor 🗸	Unli 🗸	Low		
З	Slip hazards from fluid on ground	Trips and falls resulting in personal injury	Major 🗸	Lab has cleanliness requirements Equipment maintenance	Unlik 🗸	Med		low cold water through experiment first to ensure no leaks or loose fittings.	Mode 🗸	Rar: 🗸	Low		
4	Electrical Shock	Electrical shock from water contacting electrical components of the experiment or internal electrical fault of the equipment	Catastrop 💙	USQ would have appropriate RCD devices. Armfield HT36 includes integrated RCD device.	Unlik 🗸	Med		Equipment power leads will have test labels checked to be in date before test commences Before test complete the Armfield RCD test as described in the instruction manual.	Catas! 🗸	Rar: V	Low		
5	Exposure to Water Borne Hazards	Sickness due to exposure to water borne hazards.	Major 🗸	Regular cleaning of rust, sludge, scale. Regular change of water	Unlik 🗸	Med		Student to view USQ records of cleaning, water changing and control plan for this risk before completing experiment.	Major 🗸	Ran 🗸	Low		

Figure C-2:: Risk register and analysis.

	tep 5 - Action Plan (for controls	not already in p	Jacej		
	Additional Controls:	Exclude from Action Plan: (repeated control)	Resources:	Persons Responsible:	Proposed Implementatio Date:
Ŀ	Review of the Armfield HT36 manual and the task specific USQ Risk Assessment		Armfield HT36 Manual and USQ 'Heat Exchanger Unit' SWP.	Terrence Clarke	19/05/2021
2	Dissertation experiement designed to use approx 50DegC maximum Temperature. Flow cold water through experiement first to ensure no leaks or loose fittings. Experiemental equipment not to be opened by student - seek technical assistance if faults found.		Access to experimental jig	Terrence Clarke	24/05/2021
8	low cold water through experiment first to ensure no leaks or loose fittings.		Access to experimental jig	Terrence Clarke	24/05/2021
1	Equipment power leads will have test labels checked to be in date before test commences Before test complete the Armfield RCD test as described in the instruction manual.		Access to experimental jig	Terrence Clarke	24/05/2021
5	Student to view USQ records of cleaning, water changing and control plan for this risk before completing experiment.		USQ Control Plan and Maintenance Records	Mohan Trada	21/05/2021
9		ttachments			
0	Click here to attach a file				
	tep 6 – Request Approval				
1	rafters Name: Terrence Clark	e		Draft Date:	19/05/2021
1	rafters Comments: Completed to	best of my knowledge. Rea	ady for Supervisor Approval		
4	ssessment Approval: All risks are marked as A faximum Residual Risk Level: Low - Manager/S	LARP upervisor Approval Rec	quired		0
1	ocument Status:	Approv	e		
	iten 6 – Approval				
1	pprovers Name: Khalid Saleh		Approvers Position Title:		
4	pprovers Comments:				
1	am satisfied that the risks are as low as reasonably	practicable and that the n	esources required will be provided.		
-	paraval Decision: Approve	Approv	. / Reject Date: 19/05/2021	Document Status:	Approve

Figure C-3: Action plan and approval.

	Base Li	Test 1	Test 2	Test 3	Test 4	Test 5	Test 6	Test 7	Test 8	Test 9	Test 10	Test 11	Test 12	Test 13	Test 14	[est 15]	fest 16
Hot Vater Sveep Divisions	2200	2200	2200	2200	2200	1900	1300	1900	1900	1300	1700	1700	1700	1700	1700	1600	1500
Hot vater edge division	8	28	38	28	8	24	24	24	24	24	22	22	22	22	22	22	52
Cold water Body Sizing	0.0026	0.003	0.0035	0.004	0.005	0.0026	0.003	0.0035	0.004	0.005	0.0026	0.003	0.0035	0.004	0.005	0.0045	0.006
Cold water corner Face Size	0.0008	0.001	0.0015	0.002	0.0025	0.0008	0.001	0.0015	0.002	0.0025	0.0008	0.001	0.0015	0.002	0.0025	0.003	0.0035
Cold water transfer face size	0.0021	0.0025	0.0025	0.0025	0.0025	0.0021	0.0025	0.0025	0.0025	0.0025	0.0021	0.0025	0.0025	0.0025	0.0025	0.003	0.0035
Resulting Elements	443487	382876	326806	261251	213804	427587	366976	310906	245351	203904	416987	356376	300306	234751	193304	176712	149892
Average X,Y,Z Convergence	2.730	2.400	1.136	2.567	5.733	3.170	2.967	1.360	2.900	6.600	3.730	3.167	1.169	3.133	8.267	5.2	9.2333
Continuity Convergence (E-0	1.750	1.150	0.900	1.190	1.600	0.850	1.900	0.600	1.300	1.800	1.900	1.200	0.380	1.250	1.900	2.8	15
Energy Convergence (E-07)	1.100	1.100	1.300	3.000	2.800	1.200	1.200	1.300	3.100	2.600	1.280	1.300	1.400	3.350	2.300	3.15	2.4
Hot Temp Out	315.26	315.23	315.27	315.51	315.66	315.29	315.23	315.27	315.49	315.62	315.28	315.23	315.27	315.49	315.6	315.67	315.58
Cold Temp Out	316.19	316.37	316.26	315.57	315.3	316.2	316.37	316.27	315.63	315.3	316.19	316.36	316.26	315.66	315.35	315.19	315.46
Hot Vater Centre (T3)	320.29	320.27	320.26	320.25	320.28	320.29	320.27	320.26	320.25	320.27	320.29	320.27	320.26	320.25	320.27	320.28	320.29
Cold Vater Center (T8)	308.02	308.13	308.01	307.37	307.23	308.02	308.13	308	307.35	307.21	308.02	308.13	808 208	307.35	307.2	307.01	307.35
Hot Vater Mass Flow Rate C	0.0499	0.0499	0.0439	0.0491	0.0499	0.0439	0.0439	0.0499	0.0439	0.0499	0.0439	0.0499	0.0439	0.0439	0.0499	0.0499	0.0439
Cold Vater Mass Flov Rate	-0.016	-0.017	-0.017	-0.016	-0.016	-0.016	-0.017	-0.017	-0.016	-0.016	-0.016	-0.017	-0.017	-0.016	-0.016	-0.017	-0.016
Hot Vater Pressure Centre	2495.7	2495.7	2495.7	2495.7	2495.7	2508.8	2508.8	2508.8	2508.8	2508.8	2565.9	2565.9	2565.9	2565.9	2565.5	2467.6	2471.8
Cold Vater Pressure Centre	-380.6	-997.5	-1013	-921.5	-957.6	-380.7	-997.4	-1013	-921.6	-957.6	-380.7	-997.4	-1013	-921.6	-958.4	-935.6	-1213
Convergence Error Represer	N/A	70	87	58%	887	%	3%	97	63%	94%	217.	744	9%	737.	7107	112.7.	119%
Temperature Error	N/A	0.117	0.04%	0.50%	0.67%	240.0	0.117	0.04%	0.487	0.66%	24010	0.117	0.04%	0.477	0.65%	0.78%	0.55%
Mass Flow Rate Error	N/A	0.16%	0.25%	2.44%	1.53%	0.00%	0.16%	0.25%	0.757	1.53%	0.00%	0.16%	0.26%	0.76%	1.537	1.24.7	2.727
Pressure Error	N/A	1.72%	3.337	6.03%	2.357	0.537	2.237	3.867	6.55%	2.87%	2.82%	4.527	6.15%	8.837	5.07%	5.72%	24.64%
Element Reduction		14%	26%	41%	20%	47.	17%	30%	45%	54%	82	20%	327	47%	56%	60%	

Appendix D – Mesh Independence Study for Heat Exchanger

Figure D-1: Mesh independence study results – for section 4.2.4.

	Base Line	Test 1	Test 2	Test 3	Test 4	Test 5	Test 6	Test 7	Test 8	Test 9
Hot Water Sweep Divisions	600	550	600	550	500	600	550	600	550	600
Hot water edge division	52	48	52	48	46	52	48	52	48	52
Cold water Body Sizing	0.0007	0.0007	0.0012	0.0012	0.0012	0.0009	0.0009	0.0011	0.0011	0.0008
Valve Face Size	0.0002	0.0002	0.0005	0.0005	0.0005	0.0003	0.0003	0.0004	0.0004	0.00025
Resulting Elements	465279	453479	303431	240165	223440	348830	290166	309910	248847	387359
Average X,Y,Z Convergence (E-06)	2.433	1.567	1.757	17.333	0.350	3.467	7.430	8.333	3.930	3.333
Continuity Convergence (E-03)	2.600	1.700	1.450	16.000	1.167	4.200	7.900	6.600	3.000	5.400
Energy Convergence (E-07)	1.200	1.300	1.300	7.000	1.000	1.900	4.000	3.500	2.300	1.800
Hot Water Mass Flow Rate Centre	0.04991	0.04991	0.04991	0.04991	0.04991	0.04991	0.04991	0.04991	0.04991	0.04991
Cold Water Mass Flow Rate Centre	-0.01614	-0.01614	-0.01597	-0.01596	-0.01604	-0.01598	-0.01601	-0.01612	-0.016	-0.01614
Hot Water Pressure Centre	54.55	54.59	54.55	54.3	54.83	54.55	54.3	54.55	54.3	54.55
Cold Water Pressure Centre	-139.235	-139.08	-257.69	-144.79	-102.78	-117.36	-139.74	-101.07	-124.2	-138.7
Subjective Pass/Fail of streamlines	Pass	Pass	Pass	Average	Average	Pass	Pass	Pass	Average	Pass
Convergence Error Representation	N/A	3%	3%	537%	0%	54%	214%	196%	56%	65%
Mass Flow Rate Error	N/A	0.00%	1.04%	1.12%	0.60%	0.94%	0.76%	0.10%	0.83%	0.04%
Wall Pressure Error	N/A	0.18%	85.08%	4.45%	26.70%	15.71%	0.82%	27.41%	11.26%	0.38%
Element Reduction		3%	35%	48%	52%	25%	38%	33%	47%	17%

Appendix E – Mesh Independence Study for Cold-water Entry Region

Figure E-1: Mesh independence study results – for section 4.5.4.

Appendix F – Local Temperature Distribution Data for Section 4.5.6

															Distance
				1	2	3	4		5	6		7	8	9	10
			Min (K)	291.5	291.491	291.501	291.4	91 29	1.49	291.5	604	291.50	3 291.4	3 291.50	1 291.502
	No val	ve	Max (K)	297.859	300.107	299.865	299.7	83 299	9.149	299.2	267	298.56	9 299.31	6 300.19	299.184
<u> </u>			Average (K)	291.299	289.73	293.898	292.7	67 292	2.598	292.5	531	292.48	7 292.55	9 292.44	4 292.31
ĕ			Min (K)	291.418	291.49	291.499	291.4	94 29	91.5	291.4	47	291.50	1 291.5	291.48	8 291.493
. A	15		Max (K)	299.896	301.377	300.866	299.2	82 301	1.142	299.3	95	300.38	6 300.87	7 299.81	7 300.177
Ξ			Average (K)	291.625	291.289	292.698	292.2	43 292	2.263	292.3	302	292.41	3 292.38	7 292.45	3 292.363
L L			Min (K)	291.499	291.493	291.5	291.3	96 291	1.501	291.4	41	291.49	9 291.50	6 291.50	1 291.525
ee l	30		Max (K)	300.23	301.527	299.313	302.6	21 300	0.599	300.1	.77	300.50	1 300.25	7 302.00	1 300.306
) j			Average (K)	291.643	288.697	292.121	292.0	04 292	2.191	292.3	22	292.28	6 292.48	9 292.32	8 292.366
S E			Min (K)	291.503	291.501	291.497	291.5	02 291	1.488	291.4	49	291.5	291.38	9 291.48	3 291.549
sitio	45		Max (K)	303.619	302.082	300.709	300.0	27 300	0.479	299.9	962	299.95	4 298.51	9 298.67	2 299.465
8 .			Average (K)	291.64	292.59	291.853	291.9	71 291	1.984	292.0)64	292.30	6 283.69	3 292.32	5 292.329
, A			Min (K)	291.488	291.499	291.503	291.5	09 29	1.51	291.5	514	291.55	1 291.52	6 291.53	9 291.706
>	60		Max (K)	300.514	302.886	299.117	300.5	34 299	9.588	300.1	.26	300.60	8 299.3	3 299.05	7 297.666
			Average (K)	291.877	290.669	291.698	291.7	/3 29	1.831	291.9	97	285.48	4 294.24	5 292.13	292.405
from the s	starting wa	II (mm)													
11	12	14	16	18	20	2	2	24		29		34	39	44	49
291.474	291.474	291.52	291.625	291.70	3 291.5	29 291	571 2	291.604	293	1.796	29	1.821	291.998	291.931	292.126
300.108	299.136	299.75	301.68	303.55	5 303.8	88 304.	931 3	305.406	305	5.998	30	6.374	305.258	306.231	307.274
292.502	292.535	292.8	1 293.246	293.53	9 293.7	74 293.	768 2	293.955	294	4.491	29	4.695	295.233	295.809	295.884
291.513	291.563	291.63	34 291.6	291.66	4 291.6	59 291	637 2	291.806	291	1.692	29	1.76	292.029	292.43	292.432
301.503	300.267	299.7	9 299.385	301.53	8 305.3	02 305.	594	304.57	306	5.287	30	6.189	306.171	305.968	305.645
292.311	292.48	292.88	37 293.363	293.81	4 293.8	55 294.	022 2	293.919	294	4.451	29	4.765	295.296	295.532	295.829
291.579	291.65	291.87	1 291.692	291.84	9 291.8	41 291	863 2	291.879	291	1.827	29	1.802	291.908	292.065	291.893
299.759	298.914	298.16	64 302.252	301.73	9 303.0	31 304.	658 3	304.185	304	4.402	30	5.794	305.918	305.744	306.28
292.351	292.598	292.89	4 293.451	293.84	1 293.6	79 293.	752 2	293.552	29	4.21	29	4.438	294.931	295.13	295.492
291.707	291.629	291.54	7 291.573	291.58	3 291.6	37 291	663	291.69	291	1.693	29	1.782	291.759	291.886	292.044
299,699	299.679	302,10	302.66	305.06	6 307.6	31 307	773	306.956	306	5.862	30	7.652	307.547	306.649	305.61
292.513	292.566	292.96	2 293.175	292.97	4 292.9	84 293	239 2	293.238	29	3.51	29	4.122	294.618	295.162	295.481
291 738	291 881	291.90	7 291 776	291 74	3 291 7	74 291	768	291 76	291	1 777	29	1 779	291 776	291 803	291 837
297 589	297 881	301 3	302 931	306.82	8 307 7	05 308	19 1	307 662	306	5 625	30	17 26	305.638	306 271	308.16
297.565	207.001	203.10	23 203 1/	292.04	5 292 7	64 202	802 1	007.002	20	006	20	3 318	203.030	294.404	204 035
292.000	232.100	255.10	255.14	252.50	232.1	292.	032 4	52.794	234	2.330	23	3.310	233.33	234.404	234.333

Figure F-1: Data set from section 4.5.6 reporting temperatures at various distances by valve angle (image split for clarity).

						Dista	nce fror	n the	e startin	ıg wall	(mm))	
					10)	20		30	40		50	60
ø			Min (K)		317	7.9	318	Γ	318	318	3	318	318
ē _	No	valve	Max (K)		325	5.5	324.8		325	325	5	325	324.4
e de			Averag	e(K	318	3.1	317.8		325	319.	.5	319.7	319.6
0 8			Min (K)		318	3.0	318.0	;]	318.1	318	.1	318.2	318.0
ig ≦	4	9.5	Max (K)		324	4.6	323.9	3	325.0	323	.2	327.7	324.3
s ufu			Averag	e(K	318	3.3	319.1	3	325.0	318.	.7	319.5	321.2
9 10			Min (K)		318	3.0	318.0	;]	318.1	318.	.3	318.3	318.1
de∕ t		25	Max (K)		326	5.9	326.2	3	327.8	326	.7	327.3	326.5
1			Averag	e(K	318	3.3	319.2	3	327.8	318.	.9	317.3	318.2
			Dis	stance	e fron	n the s	tarting w	all (п	nm)				
70	80	90	100	110	0	120	13	0	140	1	50	170	190
318	318	318	318	31	8	318	31	8	318		318	318	318
324.8	326.2	323.8	325	324	14	3261	6 320	18	326.3	2 33	24.2	325.6	324.4

Appendix G – Local Temperature Distribution Data for Section 5.6.2

			Dia	stance fro	m the star	ting wall (π	חח)			
70	80	90	100	110	120	130	140	150	170	190
318	318	318	318	318	318	318	318	318	318	318
324.8	326.2	323.8	325	324.4	326.6	324.8	326.3	324.2	325.6	324.4
319.6	319.6	319.2	319.1	318.8	318.6	317.8	318.7	318.9	319.5	319.6
318.0	318.0	318.0	318.0	318.0	318.0	318.0	318.0	318.0	318.0	318.1
328.1	325.3	327.2	325.0	327.4	327.5	323.9	327.6	325.0	326.2	327.5
322.3	320.4	321.1	320.3	319.6	319.4	319.1	319.8	319.1	319.4	319.2
318.1	318.0	318.0	318.0	318.0	318.0	318.0	318.0	318.0	318.0	318.1
326.7	324.6	326.6	324.4	327.2	326.2	326.2	327.8	325.3	327.3	327.5
317.5	316.8	312.9	320.5	321.7	319.7	319.2	320.1	319.1	319.3	319.2

Distance from the starting wall (mm)													
210	230	250	270	290	340	390	440	490	540	590			
318.1	318.2	318.3	318.4	318.5	318.5	318.5	318.4	318.5	318.4	318.5			
326.8	325.6	326.1	325.7	324.8	326.1	326.4	326.1	327.8	327.3	327.1			
319.4	319.2	318.9	319.7	320	320.1	319.8	320.8	319.9	321.1	320.8			
318.1	318.2	318.2	318.3	318.4	318.3	318.4	318.4	318.4	318.4	318.5			
327.7	325.5	325.9	327.5	328.3	328.3	329.0	327.3	327.8	327.0	328.2			
319.6	319.4	319.9	320.3	320.7	321.5	320.5	320.3	321.0	321.0	320.4			
318.2	318.3	318.2	318.5	318.4	318.4	318.5	318.5	318.4	318.5	318.5			
327.7	325.1	324.8	327.7	328.5	328.9	329.3	328.0	328.7	327.1	327.5			
319.6	319.6	320.0	320.5	321.3	321.6	320.5	320.4	320.9	320.8	320.4			

Figure G-1: Data set from section 5.6.2 reporting temperatures at various distances by valve angle (image split for clarity).

	Base Line	Test 1	Test 2	Test 3	Test 4	Test 5	Test 6	Test 7	Test 8	Test 9	Test 10	Test 11	Test 12	Test 13	Test 14	Test 15	Test 16
Hot Water Sweep Divisions	default	default	default	default	default	default	default	default	default	default	default	default	default	default	default	default	default
Hot water edge division	36	36	36	36	36	36	32	32	32	32	32	32	28	28	28	28	21
Cold water Body Sizing	0.008	0.0085	600.0	0.01	0.015	0.02	0.008	0.0085	600.0	0.01	0.015	0.02	0.008	0.009	0.01	0.15	0.01
Resulting Elements	452359	400417	363067	315818	264605	215969	443927	370694	355725	285915	227334	189666	444563	316421	237560	108643	237426
Average X,Y,Z Convergence (E-06)	0.140	0.253	1.691	1.550	2.300	0.353	0.353	0.018	0.135	0.654	0.077	0.137	0.225	0.714	1.830	3.413	0.275
Continuity Convergence (E-03)	0.384	1.040	5.570	6.950	8.830	0.150	0.150	0.008	0.398	2.500	0.370	0.481	0.791	2.970	7.260	9.500	1.290
Energy Convergence (E-07)	0.068	1.826	1.988	3.190	3.620	0.690	0.366	0.003	1.955	0.940	1.384	0.210	0.377	0.550	2.950	4.420	1.210
Hot Water Mass Flow Rate Exit	-38.11	-38.11	-38.11	-38.11	-38.11	-38.11	-38.11	-38.11	-38.11	-38.11	-38.11	-38.11	-38.11	-38.11	-38.11	-38.11	-38.11
Cold Water Mass Flow Rate Exit	-4.23	-4.23	-4.23	-4.23	-4.23	-4.23	-4.23	-4.23	-4.23	-4.23	-4.23	-4.23	-4.23	-4.23	-4.23	-4.23	-4.23
Hot Water Mass Flow Rate Centre	38.11	38.11	38.11	38.11	38.11	38.11	38.11	38.11	38.11	38.11	38.11	38.11	38.11	38.11	38.11	38.11	38.11
Cold Water Mass Flow Rate Centre	-4.22515	-4.22592	-4.23	-4.228	-4.233	-4.219	-4.226	-4.23	-4.217	-4.228	-4.22	-4.226	-4.228	-4.228	-4.199	-4.189	-4.198
Hot Water Pressure Centre	1402.67	1402.63	1403	1403	1403	1403	1405	1404	1405	1405	1405	1405	1405	1409	1402	1401	1402
Cold Water Pressure Centre	23.8396	24.9467	21.55	13.41	19.7	25.52	25.71	27.25	20.47	16.89	24.51	27.32	25.95	19.16	17.8	21.59	16.22
Hot Water Outlet Temperature	358.848	358.846	358.8	358.9	358.9	358.9	358.8	358.9	358.9	358.9	358.9	358.9	358.8	358.9	358.9	358.9	358.9
Cold Water Outlet Temperature	320.08	320.1	320.1	320.1	320.1	320.1	320.1	320	320.1	320	320	320	320.1	320	320	319.9	320
Subjective Pass/Fail of streamlines	Pass	Pass	Pass	Pass	Poor	Poor	Pass	Pass	Pass	Poor	Poor	Poor	Pass	Poor	Poor	Poor	Poor
Convergence Error Representation	N/A	952%	1768%	2448%	3002%	358%	198%	0%	933%	737%	650%	79%	208%	599%	2423%	3720%	675%
Mass Flow Rate Error	N/A	0.02%	0.11%	0.07%	0.19%	0.15%	0.02%	0.11%	0.19%	0.07%	0.12%	0.02%	0.07%	0.07%	0.62%	0.86%	0.64%
Wall Pressure Error	N/A	4.65%	9.63%	43.77%	17.39%	7.07%	8.01%	14.40%	14.30%	29.32%	2.98%	14.77%	9.02%	20.08%	25.38%	9.56%	32.01%
Outlet Temperature Error	N/A	0.01%	0.02%	0.02%	0.02%	0.02%	0.02%	0.04%	0.02%	0.04%	0.04%	0.04%	0.02%	0.04%	0.04%	0.07%	0.04%
Element Reduction		11%	20%	30%	42%	52%	2%	18%	21%	37%	50%	58%	2%	30%	47%	76%	48%

Appendix H – Mesh Independence Study for Scaled Entry Region

Figure H-1: Mesh independence study results – for section 5.6.1.

	530 550	327.2 326.1	326.7 326.7	325.7 326.4	326.2 326.0	326.1 325.8	326.1 325.8	326.6 326.8	326.6 327.8	326.2 326.8	326.1 326.3	327.1 327.7	327.1 326.6	329.5 327.3	326.1 326.4	329.1 327.6	327.8 327.7	329.3 329.4	379 7 330 9
	510	328	329.9	328.9	329.4	329.6	329.6	330.0	329.7	329.7	329.4	329.7	329.9	329.8	329.7	329.0	328.3	329.2	3788
	490	327.8	326.4	326.2	326.7	327.2	327.2	328.0	329.0	328.4	327.8	328.1	328.3	327.4	328.7	327.5	327.4	328.4	3793
	470	326.5	326.8	326.2	326.1	327.4	327.4	328.1	326.3	329.8	326.4	328.4	327.0	327.8	327.0	326.5	327.3	329.0	328.1
	450	326	325.9	325.7	325.3	326.6	326.6	327.2	325.2	327.0	326.7	326.3	325.3	327.4	327.0	326.7	327.2	328.4	3 975
	430	327.2	325.5	325.3	326.5	326.1	326.1	326.3	326.1	326.7	326.9	327.4	327.2	326.8	328.4	326.7	328.2	328.3	377 4
all (mm)	410	327	327.9	328.5	326.8	328.6	328.6	329.7	328.2	328.5	329.3	329.1	328.5	328.2	328.7	328.1	327.8	328.8	3285
Starting W	390	326.4	328.3	327.9	328.0	328.3	328.3	329.4	328.5	328.6	328.0	328.4	329.3	328.8	329.3	327.9	328.3	328.2	3277
from the S	370	326.6	328.4	326.8	327.5	327.4	327.4	327.7	327.1	327.5	327.6	328.9	328.0	327.3	327.8	328.4	327.2	328.0	328.4
Distance	350	325.8	327.3	327.2	326.3	326.8	326.8	328.1	327.2	327.5	327.2	327.4	326.9	327.4	326.8	326.2	327.5	327.8	329.0
	330	326.1	326.8	326.9	327.2	327.1	327.1	327.2	327.4	326.8	326.8	326.9	326.9	326.5	327.0	327.1	327.5	326.1	327.4
	310	325.1	327.8	327.2	327.4	328.1	328.1	327.5	328.2	327.1	327.9	327.0	327.4	326.3	326.8	327.2	326.7	326.6	326.8
	290	324.8	327.8	327.6	328.2	328.0	328.0	327.8	328.0	327.6	327.9	328.2	328.2	329.2	328.5	328.6	327.4	327.8	328.5
	270	325.7	328.1	327.4	327.8	327.8	327.8	327.6	327.9	327.8	327.6	327.0	327.2	328.5	327.7	326.9	329.4	327.8	328.1
	250	326.1	325.0	325.8	325.4	324.8	324.8	325.9	326.9	325.6	325.0	326.1	325.5	327.2	324.8	325.5	325.4	325.6	324.9
	230	325.6	325.7	324.7	325.1	324.1	324.1	324.7	324.3	325.6	326.1	325.0	325.3	325.0	325.1	325.9	324.7	324.1	373.6
	210	326.8	329.1	327.0	328.7	327.1	327.1	327.3	327.4	329.7	328.3	327.9	327.8	326.8	327.7	327.6	326.7	327.4	326.5
anoraturo (V)	uperature (N)	0	5	10	15	20	25	30	35	40	45	50	55	60	65	70	75	80	85
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Appendix I – Temperature Distribution Data for Section 6.1

Figure 1-1: Mesh independence study results – for section 5.6.1.